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3 **TRUE GRASP: Actors visualize and explore hidden limitations of an apparent win-win**  
4 **land management strategy in a MAB Reserve**  
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59 **Highlights**  
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61 Participatory multi-actor approach towards decision making  
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64 Agent-based modeling for long-term rural land use planning  
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66 Short-term benefits vs. long-term undesired regime shifts, how can we manage trade-offs?  
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70 **Abstract**

71 Win-win solutions might be short-lived. Government permission for smallholder farmers to extract  
72 and sell resin from a pine savanna biosphere-reserve in Mexico has settled a long dispute among  
73 different stakeholders in the short-term, however forest production and conservation beyond 20  
74 years are compromised due to low pine recruitment caused by competition with exotic grasses.  
75 Grass control practiced by farmers through grazing and fire has previously been discouraged by  
76 conservation authorities, which inadvertently limits long-term pine conservation and use. We  
77 describe the participatory design, rationale and simulation attributes of an educational, interactive,  
78 agent-based model that explores suites of management options and their economic and ecological  
79 outputs. We present and analyze the outcomes of four simulation workshops, where farmers and  
80 external-actors better grasped the complex ecological interactions involved in conserving and  
81 using pines in grazed pine savanna with exotic grasses, and discuss these findings with a long-term  
82 vision and tradeoff analysis approach.  
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92 **Keywords:**

93 Agent-based model, cattle in forests, decision making, forest management tradeoffs, participatory  
94 modeling, smallholder farmers  
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98 **Software availability**  
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100 The agent-based model TRUE GRASP is available (with restricted access during the review  
101 process of this paper) online at CoMSES Net / OpenABM, following this link:  
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103 <https://www.comses.net/codebase-release/6d4a0b9e-3105-47f1-989d-7d7c5c62643c/download/>  
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115 True Grasp, was developed in NetLogo language, program version 5.2.1. Developers of True  
116 Grasp are Marco Braasch ([marcobraasch@gmail.com](mailto:marcobraasch@gmail.com)) and Luis Garcia-Barrios  
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## 122 **1. Introduction**

123 The Man and the Biosphere Reserve (MABR) Program is a worldwide program formally  
124 implemented in the 1970s as a space for accomplishing both paradigmatic rural development and  
125 protection of nature (UNESCO, 1996). In Mexico, this program incorporated many territories  
126 occupied by smallholder farmers within a new model of conservation by decree to improve the  
127 social and economic well-being of populations. It was supposed to promote economic, social and  
128 environmental policies to allow families, long-established in these territories to sustain decent  
129 livelihoods by creating or supporting agroforestry or silvopastoral landscapes in buffer zones of  
130 MABR, serving as high quality matrices for conservation (Bouamrane et al., 2016; Cruz-Morales,  
131 2014; Martín-López et al., 2011). Achieving this goal has been at best problematic from the very  
132 beginning (Cagri, 1976); reasons range from stark conflict among actors related to possession or  
133 control over land, to poor understanding and agreement over the effects of land management  
134 strategies on ecosystems and smallholder farmers' livelihoods (Adams, 2004; Cruz-Morales, 2014;  
135 García-Barrios and González-Espinosa, 2017; Ma et al., 2009; Wittmer et al., 2006).  
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145 In this context, win-win land management solutions in MABs are desirable but unusual. When  
146 pathways are reasonably accepted by most or all parties, they may represent progress in some  
147 dimensions (Plummer et al., 2017) but will likely generate new issues and tradeoffs elsewhere,  
148 something to be expected in any complex social-ecological system (Agrawal and Ostrom, 2001;  
149 DeFries et al., 2007; Martín-López et al., 2011). More importantly, some emerging issues might  
150 work directly against the previously agreed-upon solution, yet this might not be easily perceived  
151 or detected, because their consequences are mid and/or long-term (Allen and Gunderson, 2011).  
152 These emerging issues commonly become invisible, get ignored or postponed for better times  
153 (swept under the carpet) by resource-stricken actors accustomed to jointly muddle through so-  
154 called wicked problems (Allen et al., 2011; Sierra-Huelsz et al., 2017). This sometimes  
155 unavoidable mishap may have dire consequences, when actors are dealing with changes in land  
156 cover, land use and/or livelihoods close to tipping points, as the situation becomes extremely  
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169 sensitive to miscalculations, unconsidered indirect interactions and short-term pragmatism  
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171 (Carpenter and Gunderson, 2001; Huber-Sannwald et al., 2012; Ribeiro Palacios et al., 2013).  
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175 In La Sepultura MABR, Chiapas, Mexico, created in 1995, anthropogenic pine savannas surround  
176 highly valued montane forest core zones as part of the buffer zone (CONANP, 2013). Prior to that  
177 year, modest pine lumber extraction and extensive cattle grazing were part of people's livelihood  
178 and intentional or accidental burning of the savanna understory was common (Guevara-Hernández  
179 et al., 2013; Navarro et al., 2017). Then, as a conservation strategy, the National Commission of  
180 Natural Protected Areas (CONANP according to its Spanish acronym) prohibited fire use, tree  
181 extraction, and livestock production in the pine savannas. However, these top-down decisions  
182 affected smallholder farmers' livelihoods and ignited a decade-long conflict between communities  
183 and CONANP (Cruz-Morales, 2014). Farmers saw no reason to protect pine trees on their land  
184 other than to avoid monetary sanctions or jail because of illegal extraction (Guevara-Hernández et  
185 al., 2013). In 2012, all parties' interests finally converged in a joint project to extract turpentine  
186 resin from adult pine trees to be sold to the AIEn del Norte Corporation. Under these new  
187 perspectives, the imposed land management strategies now made more sense to smallholder  
188 farmers, at least for a 20-year time span ahead during which current adult pine trees would yield a  
189 marketable oily product. Yet, a hidden contradiction remained: in most pine stands, small native  
190 grasses and herbs have long been outcompeted by tall exotic grasses; in the absence of fire and  
191 grazing, they can be a significant obstacle for recruiting future generations of productive adult pine  
192 trees (Braasch et al., 2017). By targeting this attractive short-term win-win solution (i.e. protecting  
193 the pines and extracting resin), actors in this partnership are paying little attention to the long-term  
194 effects or do not reach consensus over strategies to deal with them. Insights from smallholder  
195 farmers and plant ecology suggest livestock grazing could create opportunities for pine recruitment  
196 but may also cause trampling damage or mortality of saplings (Archer et al., 2017; Braasch et al.,  
197 2017; Van Langevelde et al., 2003; Werner, 2005).  
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213 Interactive agent-based simulation models (ABM) and socioecological board-games have emerged  
214 within different social learning frameworks, e.g. the Companion Modelling approach methodology  
215 (ComMod; Etienne et al., 2014) has useful participatory education tools such as role playing games  
216 (RPG) that facilitate communication and reflection among those involved in resource  
217 management, and promote a common knowledge ground from where to build effective  
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227 management and governance (Le Page et al., 2010; Etienne et al., 2011; Garcia-Barrios et al.,  
228 2017, 2015, 2011). Some of these frameworks and tools have allowed smallholder farmers and  
229 other actors to simulate and jointly explore land use and management options in rural small-holder  
230 territories (Barnaud et al., 2013; Berthet et al., 2016; Etienne, 2014; Villamor and van Noordwijk,  
231 2011) and more specifically in those contiguous or within MABR (Bouamrane et al., 2016;  
232 Perrotton et al., 2017).

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238 ABMs are currently used in many fields of scientific research, education and policy making as  
239 extremely powerful tools to better grasp complex processes; an ever-growing model library is  
240 currently available (Rollins et al., 2014). Many social, educational and technical challenges  
241 associated with ABM remain, spanning from their proper development to their use as multi-actor  
242 social learning tools within rural settings (Barnaud et al. 2013; Becu et al. 2007; García-Barrios et  
243 al. 2017). Le Page and Perrotton (2017) fruitfully discuss the different objectives and tradeoffs  
244 involved in abstract, stylized and realistic agent-based models, and stress that the requirements and  
245 purposes of social learning should guide the choice, construction and use of these simulation  
246 models in multi-actor, land-stewardship processes.

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253 Since 2007, the second author (LGB) has been leading participatory multidisciplinary research in  
254 La Sepultura MABR, with special emphasis in the social and ecological consequences of land use  
255 innovations meant to reconcile livelihoods and conservation (García-Barrios and González-  
256 Espinosa 2017; Valencia et al., 2015, 2014; Zabala et al., 2017). In this process, a number of agent-  
257 based models (Speelman et al., 2014a, b; Speelman and García-Barrios, 2010) and socio-  
258 ecological board games (Garcia-Barrios et al., 2017, 2015, 2011) have been developed. For this  
259 study, starting in 2014, we were welcomed by actors to follow and support the resin production  
260 project and we engaged in participatory research comprising field transects, forest inventories,  
261 ecological experiments, farmer surveys, agent-based modelling, and scenario simulation  
262 workshops to address the following questions: Do actors consider the pine savanna and resin  
263 (turpentine) extraction a short- or long-term livelihood and conservation option? Is pine  
264 recruitment actually lower where exotic grass is dominant? Is low pine recruitment a critical issue  
265 for the resin project, and for which actors? What management options for controlling exotic grass  
266 are preferred by different types of actors? What are potential short and long-term tradeoffs of these  
267 management options?

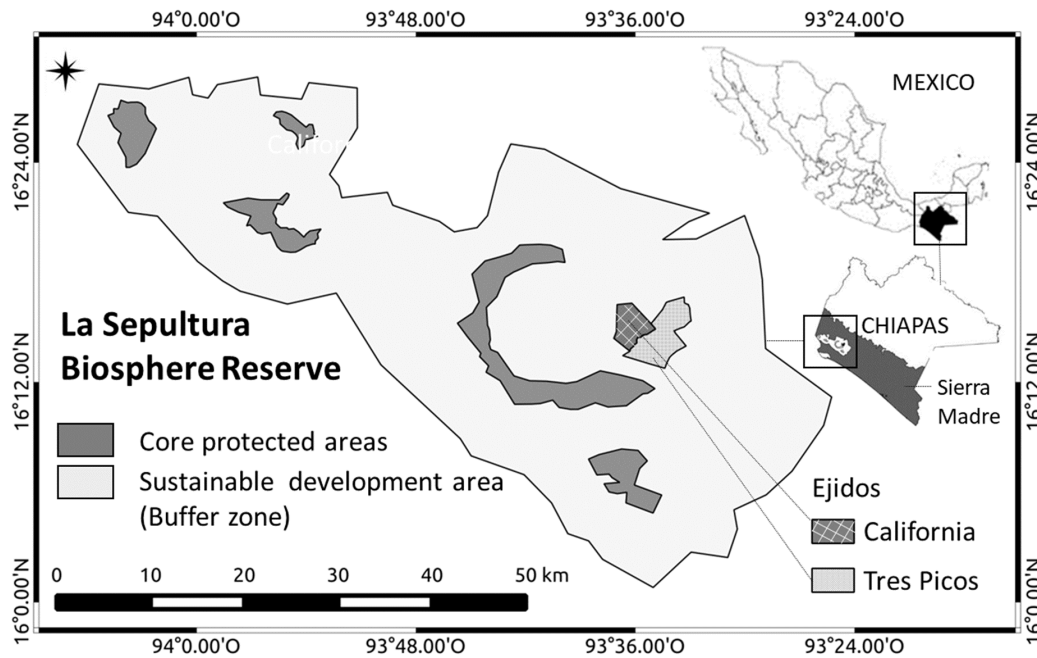
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283 We described in detail the anthropogenic origin of the pine savanna (Braasch et al. 2017); we  
284 showed that current pine population structure and low recruitment due to dense exotic grass cover  
285 cannot support long-term resin production. Furthermore, we presented experimental evidence that  
286 cattle grazing in the savanna may have both positive and negative effects on recruitment. Here, we  
287 describe and discuss the development and use of an interactive agent-based model with farmers  
288 and other actors, to help address the above questions.  
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294 The objectives of this paper are to (a) describe the interactive, stylized agent-based model TRUE  
295 GRASP (Tree Recruitment Under Exotic GRASs in the Pine-savanna) and its background,  
296 rationale and main attributes; (b) present and discuss the outcomes of four TRUE GRASP  
297 simulation workshops held separately and jointly with smallholder farmers and external actors to  
298 address in a stylized, qualitative way the questions listed above and to support social learning of  
299 all parties involved, including ourselves.  
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## 304 305 **2 Methods**

### 306 *2.1 Study area*

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308 The study was carried out in the pine savanna under *ejido* tenure (a mixture of private and  
309 communal land) belonging to the rural towns of California and Tres Picos, located in the buffer  
310 zone of La Sepultura Biosphere Reserve (SBR) in Chiapas, Mexico (16°16'40" - 16°12'40"N and  
311 93°37'10" - 93°32'55"W; **Fig. 1**).  
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**Fig. 1** La Sepultura Biosphere Reserve in the Sierra Madre mountain range of Chiapas, Mexico with the protected core areas and buffer zone and the location of the two *ejidos* California and Tres Picos, where this study was carried out.

The topography of the area is highly irregular with steep slopes. Dominant soils are Regosols and Cambisols over granitic rock. The tropical climate is seasonally dry. Annual mean temperature ranges between 25 and 28 °C. Average annual precipitation reaches  $2003 \pm 484$  mm (30-year average; CONAGUA, 2015). The pine savanna is located between 900 and 1100 m above sea level. Both communities were established during the 1970s by landless people (Cruz-Morales 2014). Since the settlement, cattle raising together with maize and bean production for self-supply and regional markets have formed part of the smallholders' livelihoods (Cruz-Morales 2014), but livestock became even more important in the late 90s, when maize prices plummeted in 1995 as a result of NAFTA (García-Barrios et al., 2009; García-Barrios and González-Espinosa, 2017). In the same year, the federal government designated a buffer zone in the SBR. Currently, the people grow mainly maize and beans for self-supply. For monetary income, they raise livestock, grow organic coffee, and more recently, extract resin from *Pinus oocarpa* Schiede ex Schltdl. Of their total land area, pine savanna is particularly important for production, as cattle raising plus resin represents a significant share of their income. In both communities, pine savanna extends close to the forest frontier in one of the core protected areas of the SBR, which consists of a highly

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biodiverse montane cloud forest ecosystem (CONANP, 2013). In the pine savanna, the most  
abundant exotic grass species are *Melinis minutiflora* P. Beauv. (“Gordura grass”) and  
*Hyparrhenia rufa* D.A. Reid (“Jaragua grass”), which were introduced to Mexico in the late 19<sup>th</sup>  
century for livestock production (Parsons, 1972). *Pinus oocarpa* dominates the pine savanna tree  
stratum (Braasch et al., 2017).

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2.2 *Extensive surveys with resin producers, main topics and analyses*

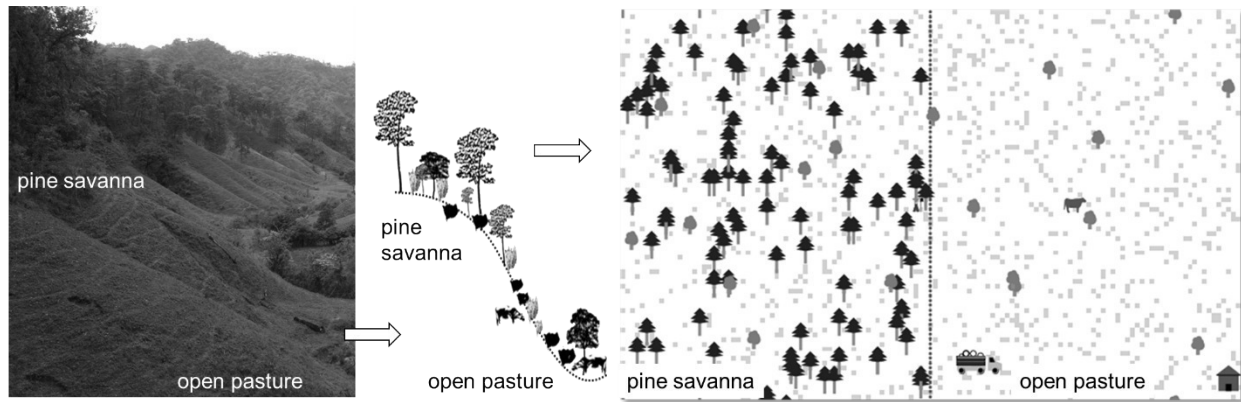
The most relevant actors related to pine savanna management are the local families (roughly 74 %  
of them are involved), the conservation authority (CONANP), and the national corporation that  
buys the turpentine (AlEn del Norte). Secondary actors are the national forestry department  
(CONAFOR), an environmental conservation and development NGO (Pronatura), and public  
research institutes (ECOSUR and Universidad Autónoma de Chapingo). The authors of this paper  
have sustained frequent interactions with all actors during the past three years, both in the field  
and in organized meetings. From these interactions, it became apparent that within and among  
these groups of actors there are different and sometimes conflicting views on the level and  
importance of pine recruitment in the savanna, and on the existence of ecological and economic  
tradeoffs associated with exotic grass management options. With the aid of questionnaires, maps,  
photos, drawings and field visits in 2016, we interviewed 52 local people involved in turpentine  
extraction (men and women of different age groups from both communities) to further clarify their  
activities; land use interests; expectations about resin extraction as a short or long-term livelihood  
option; knowledge on ecological factors affecting pine recruitment; tradeoffs involved in each  
exotic grass control measure (controlled fire, weeding, grazing); and preferred control option.  
Surveys were analyzed with descriptive statistics and results were used to build TRUE GRASP  
and design farmer and multi-actor workshops. Farmers were involved in the modelling process:  
Most resin producers participated in defining its general purpose; fifty-two discussed with  
researchers the relevant processes involved and provided empirical data, which were later stylized  
by researchers as model parameters; ten farmers tested the user-interface and validated the model’s  
qualitative behavior and outcomes in a pre-workshop meeting. All along they showed interest in  
research oriented towards exploring management options for recruitment. The day they attended  
the single actor workshop, farmers were invited to actively work all day and thus received six USD  
covering a local daily salary.

## 2.3. *The TRUE GRASP agent-based model*

### 2.3.1. *Virtual world and components*

In this section, we provide a short summary of how TRUE GRASP was designed and describe its components. For more detail see the Overview, Design concepts, and Details (ODD) protocol in Supplementary data (Appendix A), where we followed the updated ODD protocol by Grimm et al. (2010) and Müller et al. (2013).

TRUE GRASP is an agent-based model created with NetLogo v.5.2.1 (Wilensky, 1999). It allows users (farmers and other actors) to set management parameters, run the simulation, observe the trajectory of relevant variables, and repeatedly reset the simulation and its parameters to stir specific trajectories towards desired ecological and productive outcomes with acceptable tradeoffs. The entire landscape of the virtual world has an extension of 81 x 129 patches (10449 cells), which represents 4-hectare of land divided into two equal parts, pine savanna and open pasture, representing typical landscapes in the SBR (**Fig. 2**). The total size of the NetLogo “World” was selected to contain a realistic initial population of 50 adult pine trees per ha of savanna, while allowing space for all other user interface features (buttons, sliders, switches, plots, monitors etc.). Each patch covered 3.8 square meters, an arbitrary but convenient size to reconcile the different spatial scales of the modeled agents and their movements (grass, fire, farmer, cattle, pine dispersion). It is worth noting that these agents’ movements are highly stylized; we deliberately avoided dubbing them with complex dispersion and search behaviors. We chose the rabbit-grass-weed algorithm (Wilenski, 2001) to produce a semi-random walk for cattle; the mushroom hunter model algorithm (Railsback and Grimm, 2012) for farmers searching pines, and Moore neighborhood colonization for grass and fire. The general assumption in this stylized approach is that – for the current purpose of the model - the intensity and consequences of interactions among all these agents reasonably and sufficiently depend on their local and global densities (albeit in nonlinear ways).



**Fig. 2** Design of the virtual world of the agent-based model TRUE GRASP based on a mountainous landscape in La Sepultura Biosphere Reserve, Chiapas, Mexico, representing 2 ha pine savanna and 2 ha of open pasture.

The pine savanna is a forest stand with an open canopy and initially contains 100 mature pine trees in two ha land. The forest understory cells (patches in NetLogo language) can be covered by the following agents representing different vegetation cover types: (1) pine seedling; (2) pine sapling; (3) exotic tall grass cell, that impedes seed germination and seedling establishment; (4) short grass cell, short-statured native grass or recently burned forest floor or exotic grass kept short by cattle grazing with all these cell occupations allowing pine seedling establishment; (5) pine needle litter or shade near adult pine trees not allowing seed germination or seedling establishment (see Supplementary data A; Fig. 2). Other agents are resin producer, cow and fire. The user embodies and assists the virtual resin producer in defining cattle load and the frequency of cattle rotation, use of fire, and manual weeding. The most relevant outputs (reported annually and cumulatively) are the number of pine seedling/saplings, mature productive resin trees, resin barrels and calves. Each iteration (time step) in the model represents one day. A thirty-year simulation with an Intel-Core i5 processor takes between 5 and 10 minutes. Several decades (50 – 100 years) of simulation can transform the pine savanna into an open pasture land if no recruitment takes place, or into a closed pine forest without grass in the understory, if tree recovery and growth is high; intermediate states are also possible. Although half of the virtual world is open pasture land, potential pine recruitment can also proceed there, albeit at a low pace.

Pine lifecycle in the savanna: each adult pine produces seeds every year; they are randomly distributed within a radius of 15 cells. A seed only germinates in short grass cells. Daily seedling

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563 growth rate is reduced as a function of surrounding exotic tall grass cells within its Moore  
564 neighborhood, which slows down the process by which the sapling becomes a young tree and is  
565 free from this competitive effect. Seedlings and saplings adjacent to trees older than 10 years die  
566 by a self-thinning process. Young trees can resist cattle trampling and fire once they reach the age  
567 of 3 and 9 years, respectively. Thus, a successfully established tree needs to have found space for  
568 germination and survive all risks (fire, trampling, competition of exotic grasses, and self-thinning  
569 by other pines) during its lifecycle. With intermediate exotic grass competition, an established new  
570 pine can be tapped for resin by the age of 25 years. An average individual pine's resin production  
571 lasts between 10 and 20 years depending on tapping intensity. In the real world, a tree face is  
572 tapped for five years, by moving the resin tapping face upwards to a maximum height of 2.5 m  
573 each year before a new tapping face is initiated at the other side of the tree. Tree diameter in the  
574 study area permits between 2 to 4 faces on a single tree (see Supplementary data A. Fig. 7).

583 By the age of 45 years, an adult tree will have exhausted its resin production and thus can be felled  
584 for lumber. Otherwise, it dies naturally at the age of around 140 years (**Fig 3**). We do not  
585 incorporate the probability of death due to bark beetles, because they are not an appreciable factor  
586 in the area.

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590 Short grass, browsed, or burnt cells: they refer to all cells on the forest floor not occupied by adult  
591 pine trees, pine-needle litter, or tall exotic grass, which can be colonized by a pine seedling under  
592 appropriate environmental (seasonal) conditions.

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596 Exotic tall grass cells: preclude pine recruitment and provide fuel for fire and fodder for cows. If  
597 in following iterations the exotic tall grass cell is covered by pine needle litter or shade, grazed by  
598 cattle or burnt, it becomes a short grass cell, which again can become an exotic tall grass cell if tall  
599 grass later recovers.

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603 Pine needle litter/shade: Exotic tall grass and short grass cells within a five-cell radius around an  
604 adult pine tree transit gradually into litter/shade cells, and do not allow seedling establishment.  
605 Only fire, manual cleaning or litter decomposition transforms the cell back to a short grass cell.  
606 Full pine leaf litter decomposition occurs two years after an old tree has died naturally or has been  
607 felled, allowing grass growth.



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619 Cow: It moves in a semi-random walk within the assigned space: pasture land, savanna, or both  
620 with or without rotation. If a cow crosses over a susceptible seedling (aged < 3 years), it tramples  
621 and kills the seedling. The cow starts with an initial energy (weight) of 1000 units. Energy is lost  
622 each time-step (day) due to movement, and energy increases only with consumption of an exotic  
623 tall grass cells. If the cow encounters insufficient exotic tall grass cells, its energy eventually falls  
624 to zero and the cow dies. If availability of exotic tall grass cells is high and the cow reaches more  
625 than 1650 units (reproductive weight), it conserves 1000 units for itself and devotes the rest to  
626 produce a calf. Each cow is calibrated to produce no more than one calf per year (see also section  
627 2.3.3). Calves do not consume grass, as they are sold and thereby removed from the virtual world.  
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629 Resin producer: Five family members (farmers) move in the savanna, searching for pines. If a  
630 farmer encounters a resin-producing tree, he taps it and harvests the resin. The farmer is initially  
631 endowed with 100 energy units, which he spends walking. Harvested resin first compensates for  
632 this energy loss (kg of resin converts into money, which covers his labor costs) and any resin  
633 surplus accumulates in the farmer's resin container. If the energy level reaches zero, the farmer  
634 quits being a resin producer. If there is a surplus of resin in the farmer's resin container (400 units  
635 [40 kg]), the harvested resin is stored in 200 kg barrels for sale and thus leaves the system. In this  
636 simulation, the resin producer is always in the savanna and moves forward one cell per time-step  
637 (day) in search of resinous trees. Although obviously unrealistic, this stylized tree search dynamic  
638 is parameterized so that the average weekly harvest of this family in the two-hectare virtual pine  
639 stand resembles average yield per week in the study area. If a farmer moves over an exotic tall  
640 grass cell, his movement is delayed, compared to a short grass cell free of obstacles and also spends  
641 more energy that decreases his net resin accumulation slightly.  
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### 656 *2.3.2 Management practices to control exotic grasses and pine needle litter*

657 Exotic grasses and pine needle litter both influence pine seedling establishment. The model  
658 considers the following management practices to overcome this constraint. The user can select  
659 among:  
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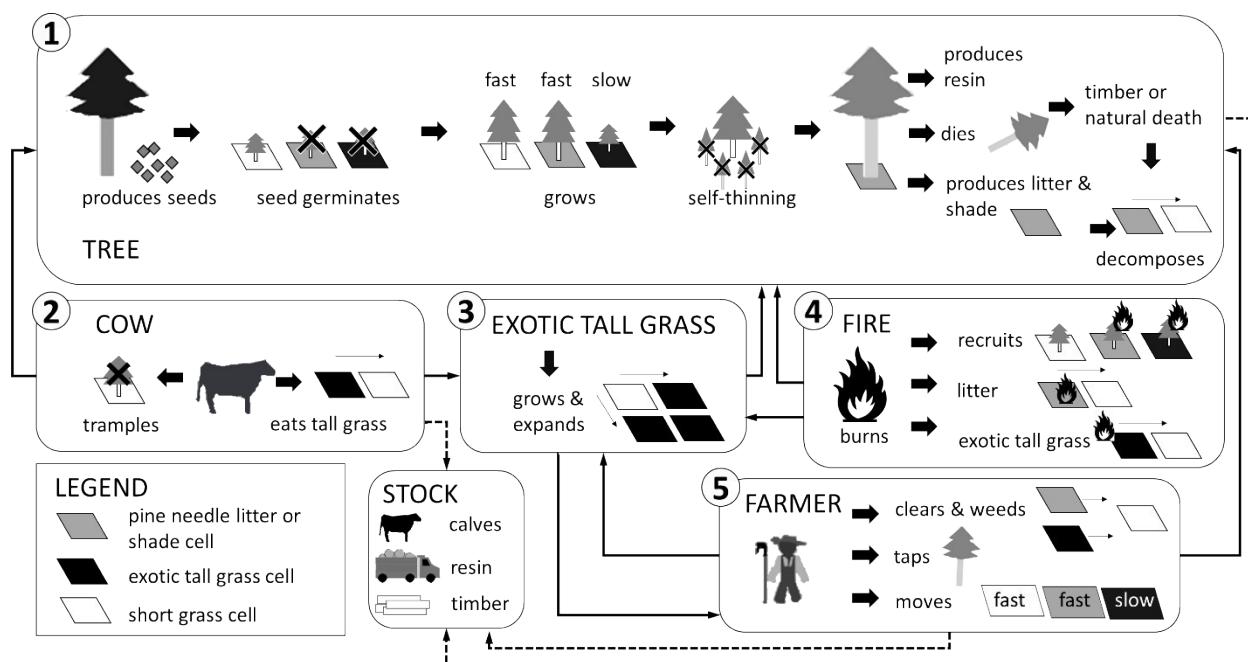
662 Manual weeding and cleaning: the farmer in the model converts by cutting manually exotic tall  
663 grass cells and cleaning pine needle litter within a 4-cell radius of a resinous tree into short grass  
664 cells. This accelerates the farmer's forward movement and opens space for seedling establishment,  
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but also reduces the farmer’s energy level due to the invested labor, which ultimately affects his net resin harvest.

**Fire:** It is simulated following the simple fire percolation model from NetLogo 5.2.1 model library (Wilensky, 1997). Fire always starts in the center cell of the virtual world and spreads with each time-step from a burning cell to any of the eight surrounding cells (Moore neighborhood) that contain fuel (exotic tall grass cells and/or pine needle litter). Fire converts these cells to burnt (short grass) cells. If fire reaches a cell covered by fuel and containing a susceptible pine tree, the latter dies. Fire can occur spontaneously each year with low probability (4 %). It can also be used as a management practice by the user, at any moment or with a fixed periodicity. In the current version of TRUE GRASP, fire is not required for pine seed germination.

**Cattle stocking and rotation frequency:** The model user chooses a certain number of cows (between zero and eight) and decides whether they occupy only the pasture land, the savanna, or both. In the second case (pasture land and savanna), cows can perambulate freely or rotate between fenced paddocks with a user-defined frequency.



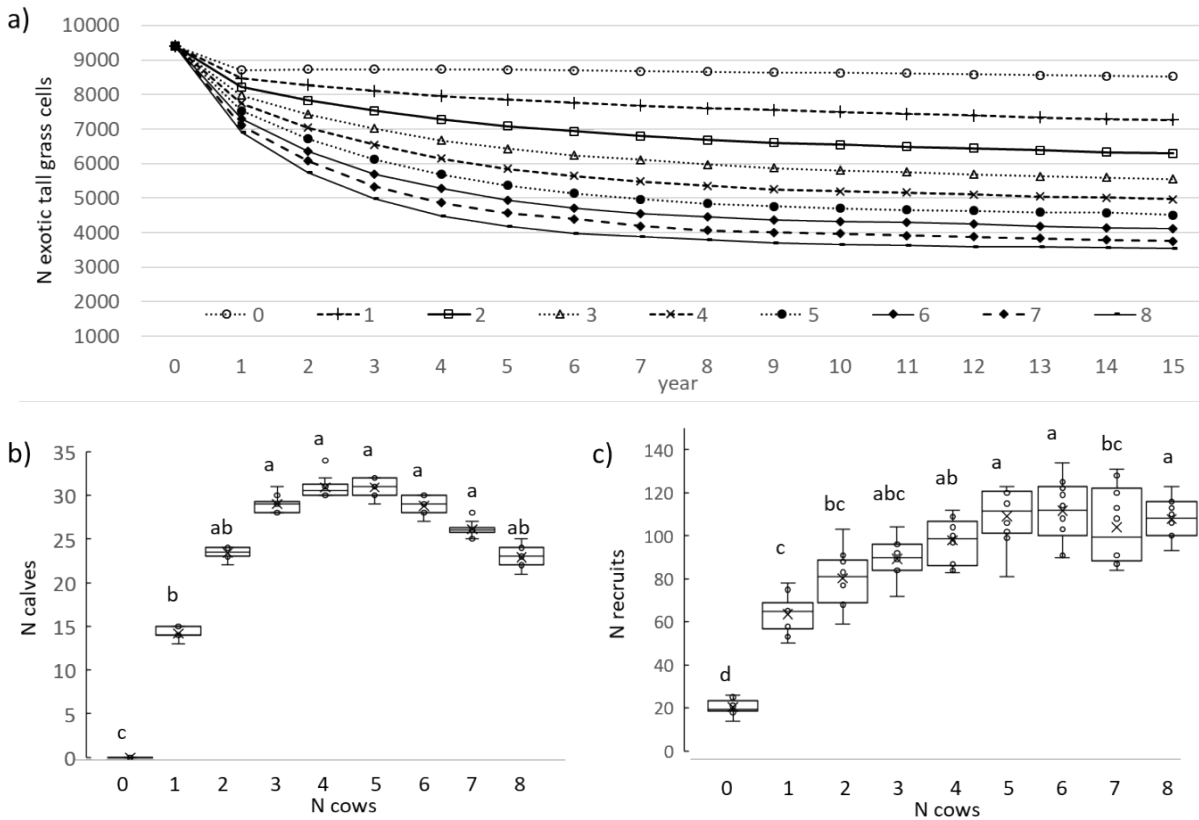
**Fig. 3** Schematic diagram of TRUE GRASP agents, processes and links between the sub-models (continuous lines) and outputs (dashed lines): 1) tree, 2) cattle, 3) exotic tall grass, 4) fire and 5) farmer.

### 2.3.3 Model parameterization and calibration

In **Appendix B**, we present a non-exhaustive but comprehensive multivariate sensitivity analysis of TRUE GRASP responses to a relevant set of parameters. Here we highlight some important aspects of the model's rationale. TRUE GRASP stylizes ecological and economic processes, and produces outputs that do not mimic the exact quantities to be expected in real-world situations (and which are still largely unknown and highly variable). It is not predictive in that sense, but its time series reproduce fairly well the short- and mid-term qualitative system behavior described by local and external actors in response to their proposed management practices in the pine savanna. Moreover, it produces reasonably well long-term scenarios that seem plausible to users.

A central purpose of the model is to allow users to explore individual and combined effects and tradeoffs of different options (fire, weeding and cattle grazing) of controlling exotic grasses in the pine savanna. Cattle grazing is currently the most contentious option and the best studied in the area, so it is better specified in the model than the other options. Actual grazing strategies in these and surrounding communities (cattle stocks, rotation rates, etc.) are context-dependent and therefore highly variable. In the SBR, smallholder farmers' cattle herds are composed of 5 to 20 animals and are rotated adaptively in their land between open pasture, savanna, or both their combination. Farmer's rule of thumb for an annual average stock which allows the production of 0.8-1.0 calf per cow per year, and that does not produce a steady long-term decline of grass cover in open pasture, is one cow per hectare of open pasture. However, detailed surveys and analysis prior to this study (Rosabal-Ayan, 2015; Valdivieso-Pérez et al. 2012; and in García-Barrios et al. unpublished database) showed that for rangelands combining open pastures and savannas, an appropriate stocking density is 0.5 cow per ha. Therefore, we selected and coupled parameters for cow reproduction and exotic grass recovery rate so that (a) a cow would produce 1.0 calf per year in 2 ha of open pasture and 0.8 calf in the combination of 1 ha of savanna and 1 ha of open pasture, and (b) a cow browsing 2 ha of open pasture would keep grass cover at an equilibrium value near 80%. Thus, more than 1 cow per 2 ha increases the percentage of short grass cells for pine recruitment at the expense of calf production, while a lower cattle load could significantly reduce space for pine recruitment with little or no gain in calf production. **Fig 4a-c** show these variables' trajectories and sensitivity analyses for different cattle stocks. **Appendix B** provides further details and sensitivity analyses for a broader set of outputs. Fire was modeled rather crudely using a simple percolation model (Wilensky, 1997), which was parameterized such that pine recruits are sensitive

to burning during the first nine years of establishment, thereby allowing reasonable recruitment under a low fire frequency regime. Weeding was parameterized to reflect the fact that it ceases to be cost-effective, when used too frequently and/or as the sole grass management practice.



**Fig. 4** a) 15-years time series with cattle stocking density of 0 to 8 cows per 4 hectares of rangeland. Each data point represents the average of 10 model runs (replicates) by the end of each year. Simulations begin with 90% of space occupied by exotic tall grass cells. See also Supplementary data B; Fig 2a-h. b) 15-year sensitivity analysis with ten model runs with livestock stocks of 0 to 8 cows for cumulative calf production. c) Cumulative pine sapling production as a function of livestock number between 0 and 8 cows. Letters over Box-Whisker plots that share one or more letter label do not differ significantly according to the Tukey HSD multiple mean comparisons test ( $\alpha = 0.05$ ).

## 2.4 Single and Multi-actor Workshops

### 2.4.1 Preliminary surveys

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843 Before starting each of three single-actor workshops with smallholder farmers of California, Tres  
844 Picos and external actors, participants were asked to (a) determine knowledge on factors affecting  
845 pine recruitment and potential tradeoffs associated with preferred management practice to control  
846 exotic tall grass cover; and (b) explain the type and consequences of emerging interactions (direct  
847 or inverse) with the help of a resin production system diagram, to make aware of tradeoffs when  
848 including e.g. cows or fire and identify the preferred effects of these components.  
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#### 853 *2.4.2 Single actor workshops*

854 Three four-hour workshops were held separately with 10 participants from California, 7  
855 participants from Tres Picos and 5 external actors respectively, on March 27 to 29, 2017. Two  
856 participants and one trained facilitator from the researcher/students team sat at each computer.  
857 Workshops included the following sessions:  
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- 861 1. Welcome, ice breaking dynamics, and sharing workshop purpose
- 862  
863 2. Presentation of an illustrated talk, leading participants from real images of the savanna landscape  
864 with its vegetation, livestock and human components to their *in-silico* representation in a NetLogo  
865 World. This was accompanied by brief simulations of the behavior of each NetLogo agent and  
866 patch.  
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868 3. Demonstration of a 15 and 30-years simulation, carried out by the first author, showed how a  
869 pine and native grass savanna (without cows) allow pine recruitment and natural development  
870 towards a closed pine forest, with its accumulated saplings, productive trees and resin production.  
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872 4. Based on the same initial spatial state, a 15 and 30-years simulation, led by the first author and  
873 executed by participants with the help of facilitators, showed the consequences on pine recruitment  
874 when substituting native grass with exotic grass considering the previous simulation setting (see  
875 3). Each participant was asked to write down his predictions on how outputs would change  
876 qualitatively (increase, remain, decrease) and then compare them with the actual simulation  
877 outcomes.  
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879 5. Eight 15-years simulation scenarios led by the first author and executed by participants and  
880 facilitators, showed both the consequences on recruitment and other outcomes of (a) burning the  
881 savanna; (b) weeding tall grass and (c) allowing cattle grazing in the whole grassland-savanna  
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899 area. Scenario 1 starts with a full ground cover of native grasses leading to a closed pine stand with  
900 abundant recruits and no exotic grass. Scenario 2 substitutes native for exotic grass and it is headed  
901 in the long run (>50 yr) to an open grassland. Scenarios 3, 4, and 5 add to scenario 2 a fire event  
902 every year, in years 1-4-8-12, and in years 1 and 12, respectively; only the last of these fire regimes  
903 creates a window for saplings to escape size-related vulnerability to fire and therefore increases  
904 recruitment. Scenarios 6 and 7 consider scenario 2 but include manual weeding around pine trees  
905 every year and in years 1 and 15, respectively. Scenario 8 also starts with scenario 2 but with 6  
906 cows grazing freely the open pasture and pine savanna (the whole NetLogo world).  
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913 6. In both farmer and external actors workshops during a thirty-minute period, pairs of participants  
914 were asked to select a set of parameters (available on the user interface) to achieve five non-trivial  
915 output goals simultaneously pre-established by researchers by year ten. These ecological-  
916 economical goals were: 40 recruits, 20 resin barrels, 18 calves, less than 25% trampled saplings,  
917 and more than 50% tall grass cover. This goal-oriented approach was chosen to increase  
918 participant's familiarity with the interface and for them to experience the many potential  
919 interconnected tradeoffs involved.  
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925 7. The "two brothers exercise": seven pairs of smallholder farmers were teamed up such that in  
926 real life one team member actually having pines and cattle, while the other one having only pines.  
927 They were told: suppose you are two young brothers A and B, whose father wishes to inherit a  
928 small herd of cattle and four hectares of land (two as pine savanna and two as open pasture). Your  
929 father says: "I am inheriting the whole property to both of you; A will own any present and future  
930 pine tree on the whole property, and B any present and future cattle and grass. It is up to you how  
931 you will manage the whole property together." To make a livelihood, by year ten A must meet 18  
932 resin barrels, 45 recruits, trampling less than 30 % and a non-negative weeding subsidy; B must  
933 meet 20 calves, and grass cover not less than 50 %. Reaching both sets of goals was possible but  
934 non-trivial and the process could drift towards one participant's interests at the expense of the  
935 other's. Participants had 30 minutes per team to select and explore parameter sets and run  
936 simulations to reach together their respective goals.  
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945 8. A thirty-minute collective reflection on the workshop experiences concluded the single actor  
946 workshop.  
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955 *2.4.3 Multi-actor joint workshop*  
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957 Participants were six smallholder farmers from the *ejidos* California and Tres Picos (3  
958 representatives from each village), three CONANP officers, two representatives from the NGO  
959 Pronatura, and the regional officer of AIEn del Norte. All 12 participants had been acquainted  
960 previously as neighbors and/or partners or observers of the resin business. After a brief reminder  
961 presentation of the model operation, each farmer was paired with an external actor to explore and  
962 reach the following three goals in a single attempt with one fifteen-year simulation: optimize  
963 sapling number, resin and calve production. The five teams were free to define their own sets of  
964 management parameters for this one-shot experiment, except for the number of cattle, which was  
965 fixed to five by researchers; an excessive and suboptimal stock would make participants confront  
966 stronger tradeoffs among outputs. The exercise was presented as a contest to see which team would  
967 achieve the best result.  
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975 Immediately after the simulation contest and reflection over the outcomes, we conducted a  
976 collective and public exercise for all actors to explore hypothetical pine savanna management  
977 choices along a decision tree, where questions were revealed to them step by step. Binomial  
978 decisions were: Is resin production a long-term project (> 50 years)? Should saplings be recruited  
979 naturally or nursed and planted? Should the main exotic grass control strategy be based on cattle  
980 stock management or grass weeding and scorching? Are such interventions collective or private  
981 decisions and endeavors? Should they be subsidized?  
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988 **3 Results**  
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990 *3.1 Farmer interviews to explore local ecological knowledge*  
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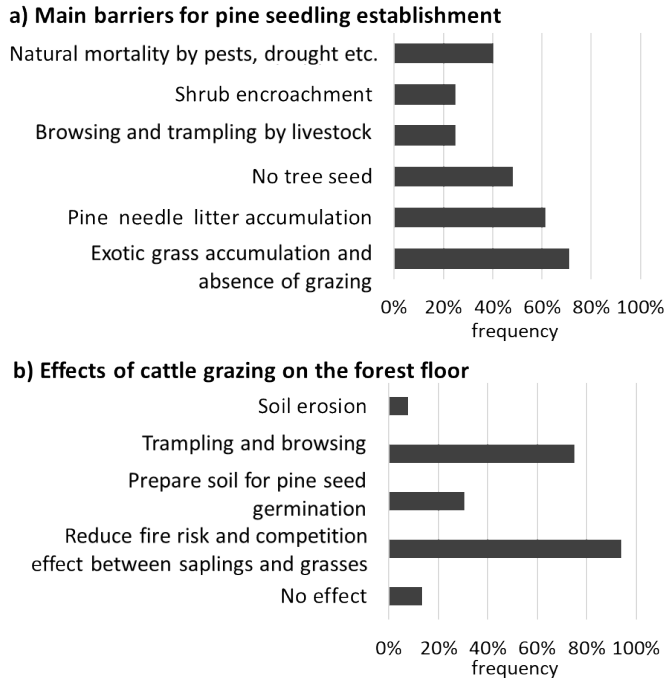
992 The majority of interviewees were males older than 40, active in resin extraction and with four to  
993 five primary activities (resin, maize, beans, coffee and livestock). Fifty-three percent of resin  
994 producers in California and Tres Picos owned livestock at that time. Most considered that the  
995 livelihood-importance of resin and coffee would grow, while maize and livestock would remain  
996 stationary. Older farmers were well aware of how the current landscape came about through  
997 selective logging and land clearing for crop and cattle production (for more detail see Braasch et  
998 al., 2017). Fifty percent envisioned local landscapes in the next ten to twenty years to consist of a  
999 semi-closed pine-oak forest combining resin, cattle and firewood production; 23% chose a closed  
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1011 pine forest dominated by *Pinus oocarpa* to increase resin production, and 19% decided for a  
1012 mixture of several land use types (pasture land, open pine-oak forest and closed pine-oak forest)  
1013 but separated in space. A few included also oak forest (6%) for firewood production.  
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1017 Regarding strategies by smallholder farmers to maintain pine stands, all interviewees said “do not  
1018 cut pine trees”; two-thirds “do not burn”, only two fifths “recruit saplings” and only one in twenty  
1019 “reforestation with nursery pine trees”. Eighty percent considered that natural pine recruitment  
1020 was appropriate at the whole *ejido* level, while 58% considered it was reasonably high in their own  
1021 pine stands. Only half of the interviewees were aware that *P. oocarpa* trees need to reach 25-40  
1022 years of age before they produce resin in this area.  
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1027 Considering pine recruitment, thirty-five percent of the interviewees considered it requires bare  
1028 soil, while 19% mentioned grazing and very few included post-fire conditions, such as fertile soil  
1029 and a seed shedding pine tree nearby. More than one third did not have an answer to the question  
1030 on regeneration niche. When asked about obstacles to recruitment (**Fig. 5a**), two-thirds considered  
1031 ungrazed exotic grass and pine leaf litter accumulation, while only one fifth included also  
1032 trampling of saplings by cows. Regarding cattle effects on forest floor (**Fig. 5b**), almost all  
1033 interviewees mentioned “grazing lowers fire risk and grass competition for saplings”; three fourths  
1034 “cattle browse and trample”; one third “trampling prepares the soil for pine germination”; 5%  
1035 “cattle causes soil erosion”, and 10% “no effect”.  
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**Fig. 5 a)** Main barriers for pine seedling establishment, and b) effects of cattle grazing on the forest floor identified by 52 small-holder farmers of the *ejidos* California and Tres Picos, La Sepultura Biosphere Reserve, Chiapas, Mexico. X-axis represents frequency with which the variable was mentioned.

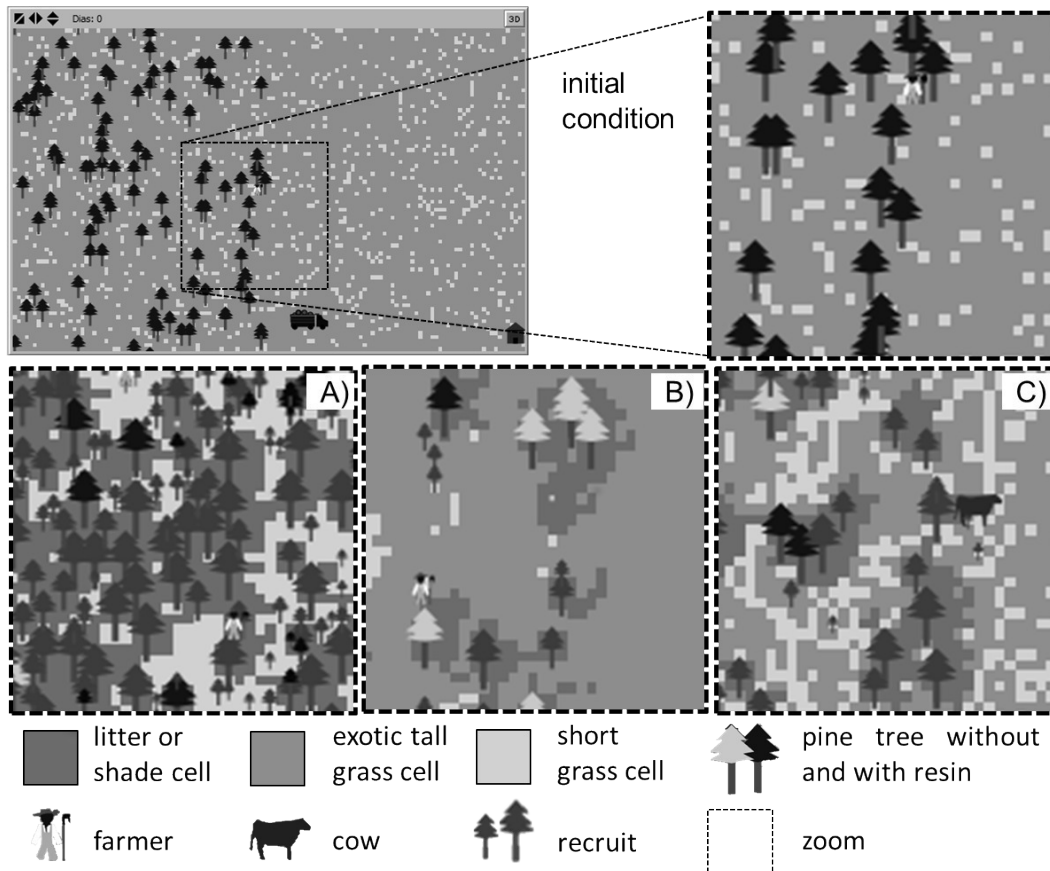
Overall, responses showed that many farmers have a broad and precise knowledge of landscape history, resin production requirements, pine life cycle and regeneration niche, factors affecting pine recruitment, and tradeoffs of cattle grazing in pine savannas for sapling establishment and growth. When considering all interviewees, knowledge and opinions were diverse, incomplete and in some cases contradictory (e.g., some farmers mentioned the positive effect of fire, “...fire is needed to stimulate tree recruitment...” but at the same time they said that they do not use it, because it is bad as it causes wildfires). Contrasting opinions occur most likely due to differences in age, activities, and livelihood-related preferences and opportunities. The rich yet incomplete ecological knowledge of smallholder farmers and the diversity of their interests regarding savanna management were useful both to guide the design and parameterization of the ABM and to further value the pertinence of facilitating farmer workshops on this matter.

### 3.2 Agent-based model capabilities

TRUE GRASP proved capable to qualitatively reproduce three different long-term scenarios of interest to the smallholder farmers for resin extraction and calf production. These were (**Table 1**): A) a baseline scenario (previous to exotic grass invasion) represented by closed pine stands with native grass/pine needle litter understory and abundant pine recruitment; B) open exotic grassland as a consequence of lack of pine recruitment; and C) exotic grass cover with moderate cattle load (two cows in four ha) and pine savanna with both high recruitment and high calf production (a win-win situation). Resin producers and other actors considered each of these scenarios relevant, and graphically (**Fig. 6**) and conceptually credible. Each scenario proved to be robust under a range of ecological and management conditions, and sensitive to threshold values of a single or several parameters potentially causing regime shifts between some of these scenarios.

Table 1. Means ( $\pm$  standard error) for the main economic and ecological outputs after 30-year simulations, considering the initial simulation condition compared to A) native grass understory without management, B) exotic grass understory without management and C) exotic grass cover with moderate cattle load (two cows). Each of the scenarios had 20 replicates.

Scenario	Resin trees (#)	Recruits (#)	Resin barrels (#)	Trampling (%)	Calves (#)	Timber (#)	Exotic tall grass (%)	Short grass (%)	Litter or shade (%)
Initial condition	100	-	-	-	-	-	90	10	0
A)	263 $\pm$ 5.3	464 $\pm$ 5.8	77 $\pm$ 0.9	0	-	57 $\pm$ 1.2	-	55 $\pm$ 0.4	45 $\pm$ 0.4
B)	24 $\pm$ 1.1	23 $\pm$ 1.2	32 $\pm$ 0.2	0	-	2 $\pm$ 2.0	82 $\pm$ 0.2	2.4 $\pm$ 0.1	16 $\pm$ 0.2
C)	53 $\pm$ 2.1	108 $\pm$ 2.9	36 $\pm$ 0.4	23 $\pm$ 1	42 $\pm$ 0.3	52 $\pm$ 1.2	58 $\pm$ 0.4	24 $\pm$ 0.2	18 $\pm$ 0.4



**Fig. 6** Possible long-term (30-year) scenarios for the pine savanna in the La Sepultura Biosphere Reserve, modeled with TRUE GRASP. Above: initial condition for all simulations, below: A) native grass understory without management, B) exotic grass understory without management and C) exotic grass cover with moderate cattle load (two cows). (Appendix B Figure 4 provides a color image for better interpretation).

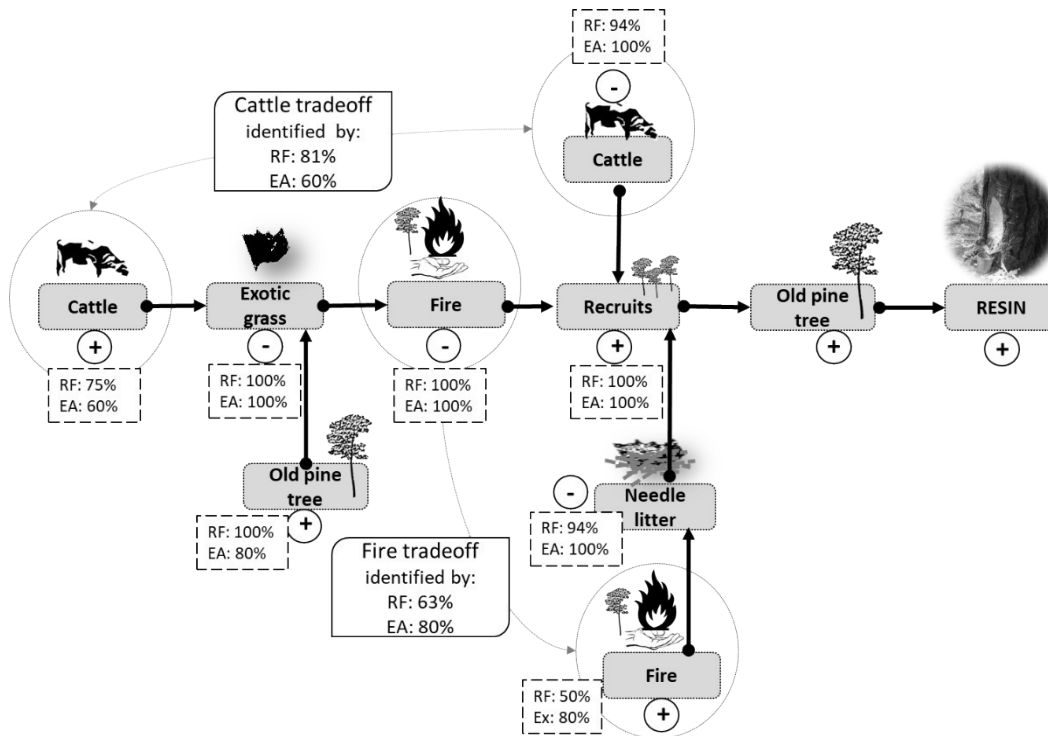
### 3.3 ABM-supported scenario exploration workshops

Seventeen persons in total participated in two farmer workshops in 2017, with the same proportion of farmers owning cattle (53%) as in the 52 interviews held in 2016. Five persons participated in an external actor workshop and 12 in a multi-actor workshop.

#### 3.3.1 Pre-agent-based model surveys and tests

Pre-ABM interviews and exercises revealed that: (a) All actors got high scores when identifying the sign of direct interactions among pine savanna silvopastoral components in **Fig 7**; yet positive effects of cattle and fire on pine recruitment were more frequently missed, the former more by external agents and the latter more by farmers. In consequence, the same trend was observed when

actors identified tradeoffs associated with cattle presence and with fire use. (b) After the fire and cattle tradeoffs were identified by actors or pointed out by facilitators, 60% of farmers and only 20% of externals saw more benefit than damage in cattle. Regarding controlled fire tradeoffs, the opposite occurred: all externals and only one elder farmer (an *ejido* founder) saw more benefits and would apply fire to control exotic grasses.

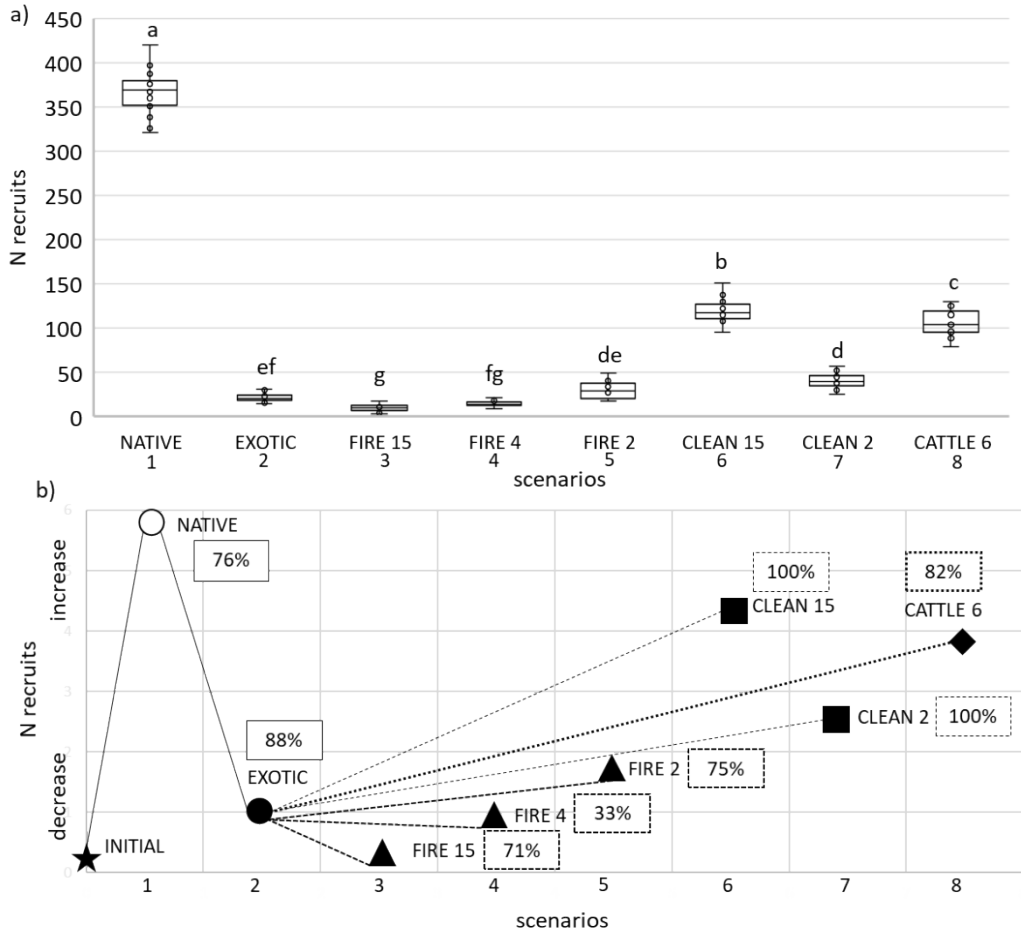


**Fig. 7** Interaction diagram of the resin production system. Black solid lines represent interactions between variables. A filled circle indicates cause and an arrowhead indicates effect. Signs indicate if the variable must increase (+) or decrease (-) to ultimately increase resin production. Cattle are in two causal relationships, which need to have different signs to increase resin. The same happens with fire. For example, fire increase reduces needle litter, which increases recruits, which increases pine trees, which increases resin. Dashed line boxes are percentage of correct scores for each interaction, by resin farmers (RF) and external actors (EA). Gray circles and arrows show tradeoffs between positive and negative effects of livestock and fire in this system. The corresponding tradeoff boxes show how many farmers or externals identified the cattle tradeoff: trampling and biomass reduction, and the fire tradeoff: sapling burning and pine leaf litter burning.

### 3.3.2 Smallholder farmers' and externals' understanding and validation of the agent-based model

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1291 **Figure 8a** shows the ABM outcomes for recruits under eight mid-term scenarios (15-years)  
1292 presented to participants for them to explore on the computer (see also Supplementary data,  
1293 Appendix B, Fig. 3 and 4). The figure shows that recruitment is very high under scenario 1, and  
1294 collapses in 2. Compared to scenario 2, recruitment increases slightly with a 12-year fire regime  
1295 but increases more with yearly weeding instead of fire, albeit with very high labor costs. When  
1296 using cattle instead of weeding, recruitment is only slightly lower, but produces additionally  
1297 around 30 calves.  
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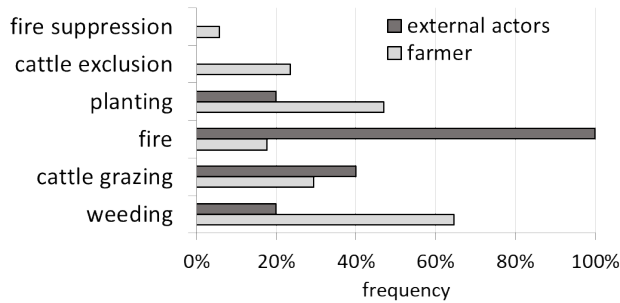
1303 Participants were presented these eight scenarios sequentially and were asked to predict prior to  
1304 each simulation, if recruitment would be higher or lower. The simulation of the native grass cover  
1305 was compared with the initial condition; exotic grass cover simulation was compared with the  
1306 output of the native grass scenario, while the predictions for fire, weeding and cattle management  
1307 were compared to the exotic grass cover scenario. **Figure 8b** shows almost all farmers predicted  
1308 qualitative outcomes correctly in each case, and only a few underestimated the damage caused by  
1309 yearly or four-year interval fires. In the course of these simulations, participants started to become  
1310 aware of other outputs as well (resin and calf production, grass cover) and the nonlinearities and  
1311 tradeoffs associated with the modeled situations. Through these predictive exercises, farmers (a)  
1312 learned the user interface and got used to interact with it; (b) developed confidence in the tool to  
1313 later explore qualitatively ranges and combinations of management options and their tradeoffs,  
1314 and (c) learned to understand the importance of discussing mid and long-term effects of  
1315 management rather than short-sighted snapshots of immediate effects.  
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**Fig. 8** a) Output of a sensitivity analysis for eight mid-term (15-years) simulations for alive recruits; 1) NATIVE grass cover without management; 2) EXOTIC grass cover without management; 3, 4, 5) FIRE (the number indicates frequency of burnings during 15 years simulation); 6, 7) CLEAN (the number indicates frequency of weeding during 15 years simulation; and 8) CATTLE, extensive grazing with six cows. Each scenario was run 20 times. Letters over Box-Whisker plots that share one or more equal letter label do not differ significantly according to the Tukey HSD multiple mean comparisons test ( $\alpha = 0.05$ ). b) Percentage (boxes) of farmers that correctly predicted an increase or decrease in pine recruitment before they ran each of the 15-years simulations. For example, 33% correctly predicted that recruits in the exotic grass with four years with fire (scenario 4) should decrease compared to exotic grass with no fire (scenario 2); 75% predicted an increase with only two years with fire (scenario 5).

Between the simulation of scenario 2 (exotic grass dominates) and the simulations with fire, weeding, and grazing scenarios, participants were asked to list their options to deal with the low

recruitment associated with unmanaged exotic grass. Around 50% of the farmers mentioned weeding and planting saplings, 24% excluding cattle from pine stands, and 25% using cattle grazing to control grass; very few mentioned controlled fire (Fig 9). In contrast, all external actors mentioned fire as an option and cattle grazing only as the second choice. Weeding and planting saplings were no real options for externals, because of high labor costs.

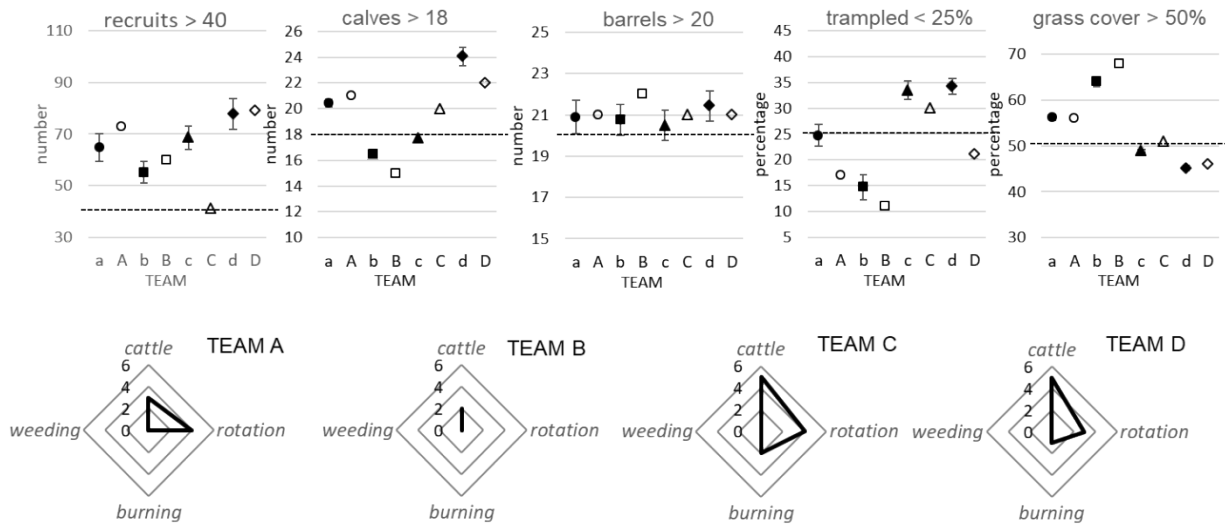


**Fig. 9** Possible management strategies to control exotic tall grass cover fostering pine recruitment, mentioned by farmers and external actors after the simulation of scenario 2, shown in Figure 8.

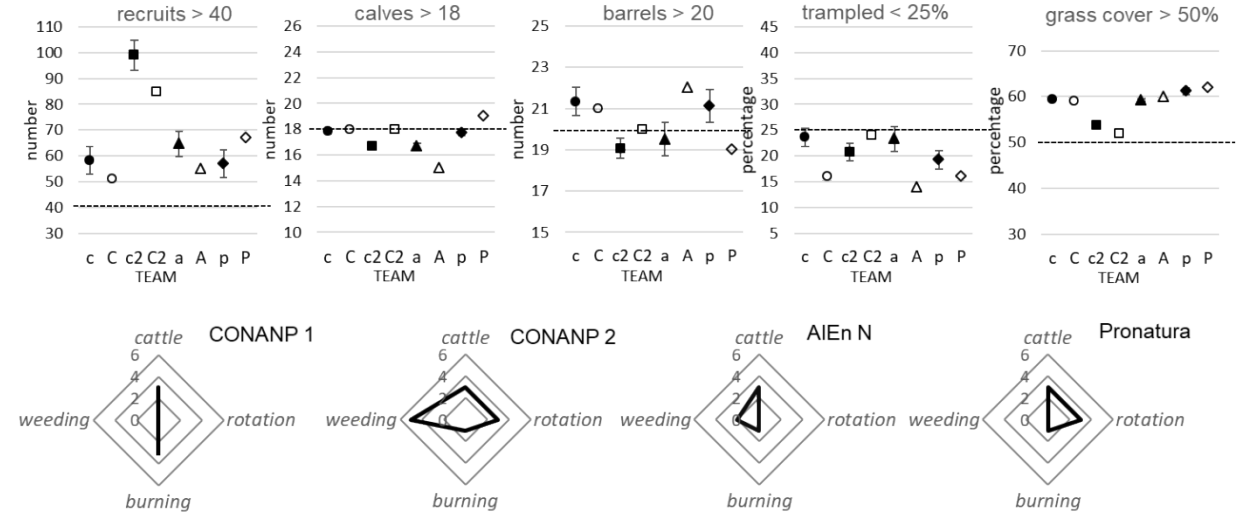
### 3.3.3 Smallholder farmers' and externals' management parameter explorations in search for pre-established ecological and economic goals

In the first goal-oriented exercise, 33% of farmer teams met three goals, 44% met four, and only 22% met all. External actors did better, 25% met four and the rest met five goals. Both groups' success frequency was very similar for recruits, barrels and calves; the difference lied in farmer's lower success due to trampling and very low grass cover, because on average, they stocked more cattle per land unit. Examples of selected management strategies and their multivariable output are presented for farmers (Fig. 10a) and externals (Fig. 10b). In both cases, the most successful model outputs combined moderate weeding with the rotation of medium (2-4 animals/ha) cattle loads.

a) Strategies of farmers



b) Strategies of externals

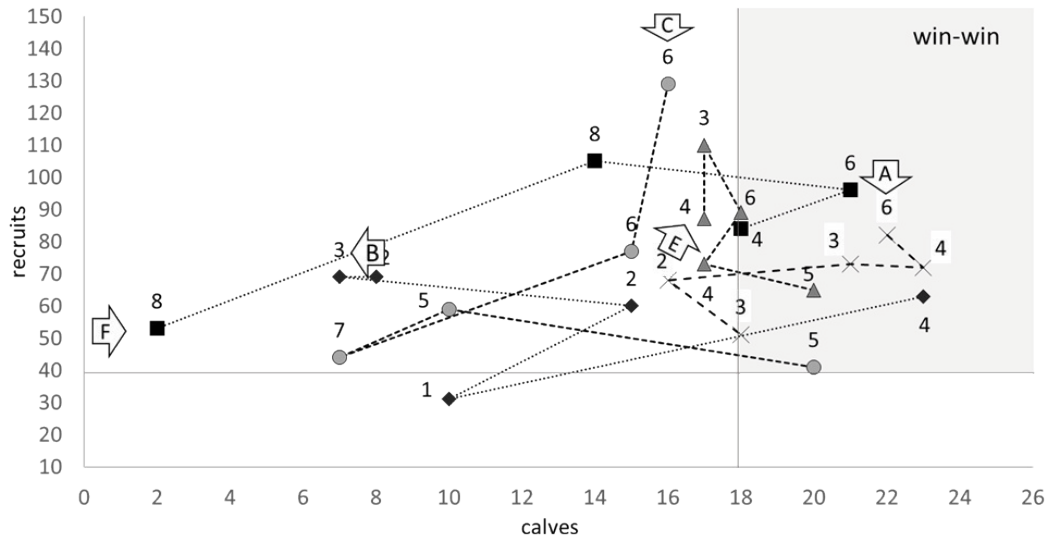


**Fig. 10** Multivariable outputs for the economic and ecological goals for a 10-years simulation by a) farmers and b) external actors. Dashed line within each graph shows the upper pre-set limit for each goal. Capital letters on x-axis and unfilled markers are the economic and ecological results from workshop participants. Lower case letters on x-axis and filled markers with error bars (confidence interval 95%) are the means of a sensitivity analysis (20 replicates) using the same management strategies selected by different participant groups shown as heading of the radar charts; above: number of cattle, right: number of rotations each year, below: number of burnings, and left: number of weeding events during a 10-years simulation.



All available management practices affect exotic grass cover directly, and this eventually affects indirectly all simulation outputs. Where cattle were included, the teams had to figure out how to deal with the direct and indirect effects of grazing in order to strike a balance between the positive and negative effects of cows on recruitment and to reach the pre-defined calf and recruit scores.

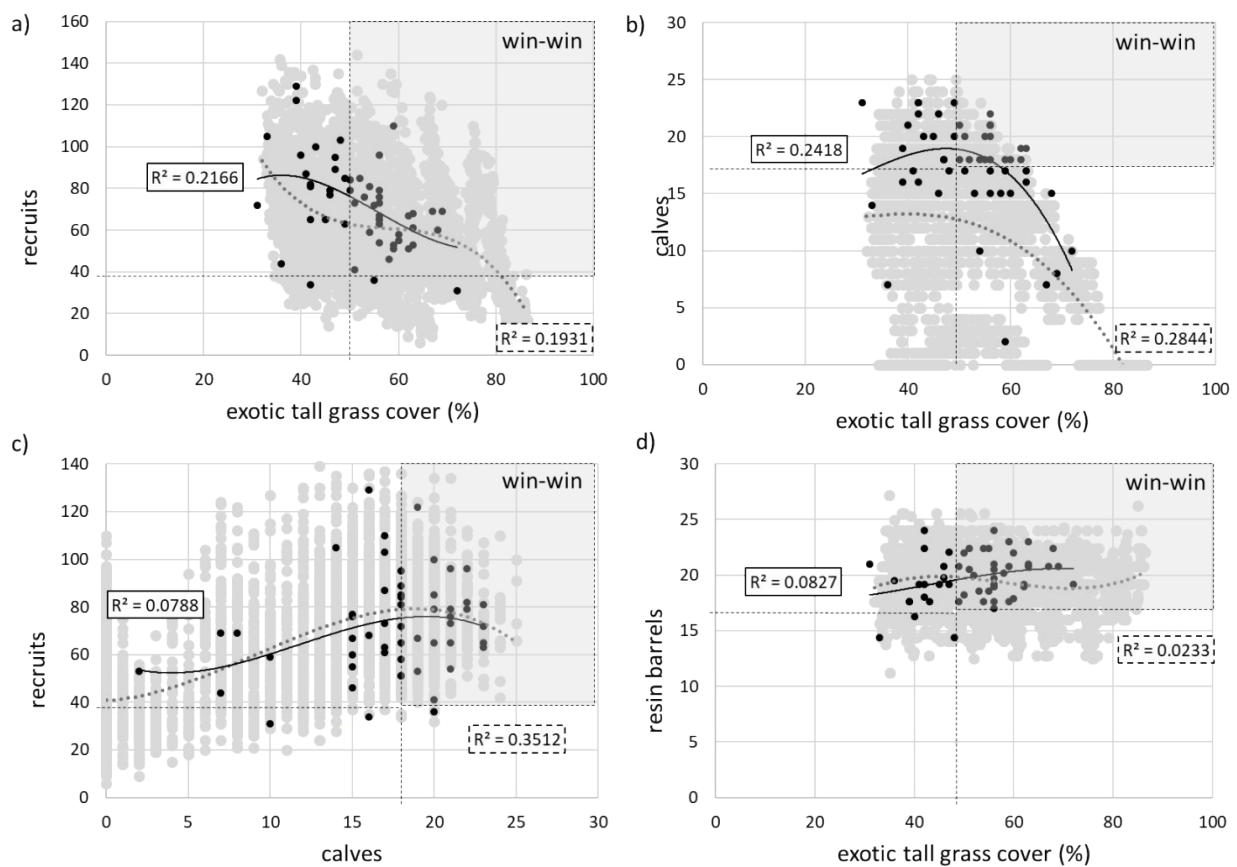
**Fig. 11** shows examples of different search strategies.



**Fig. 11** Examples of farmers search path to achieve scores for calf and recruit production after a 10-years simulation, balancing the negative and positive effects of livestock grazing. Lines represent the pathway of a team, starting at the arrow (team name A-F), each marker states an attempt, and the number above the marker indicates the initial number of cows. The second quadrant (grey box) is the area where both recruit and calf production goals are met. Because of a fixed time limit for the exercise, not all teams reached five attempts.

More generally, **Fig. 12a-d** shows as grey clouds the relations (and nonlinear tradeoffs) between some of the model's output sets, produced by 3240 parameter combinations available to participants, for fire frequency (0, 1, 2, 3, 5 and 10 burnings), weeding frequency (0, 2, 3, 5 and 10 weedings), cattle loads (0 to 8 cows), and rotation frequency (0, 1, 2, 3, 4, 6 and 12 per year). In these ten-years scenarios, reduction in exotic grass is associated to broad and nonlinear sets of responses for both recruits and calves (**Fig 12a, b**), produced by a myriad of ways, how management options can be combined; this, in turn, defines a relation between recruit and calf sets that on average turns from synergistic to antagonistic (**Fig 12c**). Superimposed on these clouds are black dots representing the actual (x,y) ordered pairs of outputs achieved by participants in all their

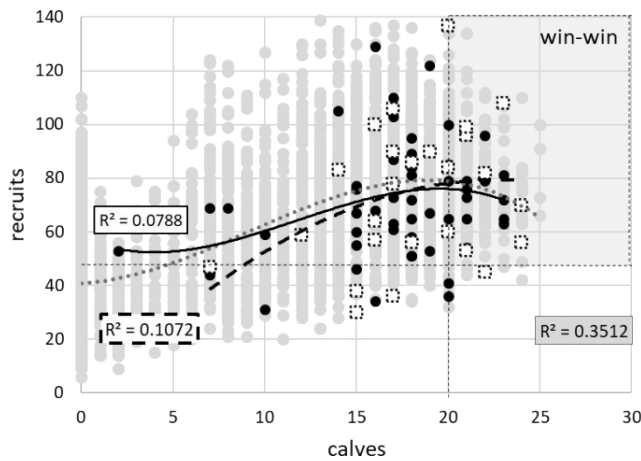
1569 attempts to reach the established goals. The latter outputs show that most participants did not  
 1570 explore parameters in a veil of ignorance and at random, but found their way in this multivariate  
 1571 and nonlinear search space towards the model's win-win scenarios for cattle production, pine stand  
 1572 persistence, and long-term resin production. Both regressions in each graph are showing the same  
 1573 trends. For the regression between resin barrels and exotic grass cover (**Fig. 12d**)  $R^2$  value  
 1574 (polynomial regression) is low, because in ten years there is yet no correlation between this set and  
 1575 the effect of recruitment on barrels is yet to come (see also Supplementary data, Appendix B, Fig.  
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1611 **Fig 12.** Regression examples of some ecological and economic outputs for 10-years simulations  
 1612 with different management strategy combinations. Gray dots, dotted lines and regression  
 1613 coefficient on the right side ( $R^2$ ) are the result of 3240 possible combinations (runs; for more detail  
 1614 see Supplementary data B, Fig. 5), Black dots, black line and  $R^2$  on the left side of the graphs are  
 1615 the results of the output variables from workshop participants.  
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1620 **3.3.4 The “two-brothers” exercise**

In the “two brothers exercise”, two out of seven teams met both brothers’ goals (calf vs. resin/recruit productions). They arrived at proper cattle loads combined with rotation and moderate fire or manual weeding (but not both), which rendered productive and cost-effective levels of exotic grass. The other five teams also arrived at 3 or 4 cows but did not meet all goals. Three penalized their income from resins due to high weeding costs; two penalized their calf production by excessively reducing grass availability by weeding and burning. In the one-actor exercise, team members had only common goals and therefore clear reasons to collaborate and deal with tradeoffs together. In this brothers exercise, they had individual goals, and there was room for transforming tradeoff management into conflict and dominance of one brother’s goals and interest over the other. Yet, search spaces of the two-brother exercise did not differ with the first exercise nor compared to the regression trend of the sensitivity analysis (**Fig. 13**). We observed collaboration to try and meet both participant’s goals although again few teams actually met them.



**Fig. 13.** Calves and recruit’s joint outputs resulting from the combination of management options explored through (a) a full sensitivity analysis with 3240 runs of possible combinations (gray dots, gray dotted line,  $R^2$  in grey box), (b) simulations done by all teams during the first exercise (black dots, black line,  $R^2$  in white box), and (c) simulations done by all teams during the two brothers exercise (white dots with dashed line, black dashed line,  $R^2$  in white dashed box).

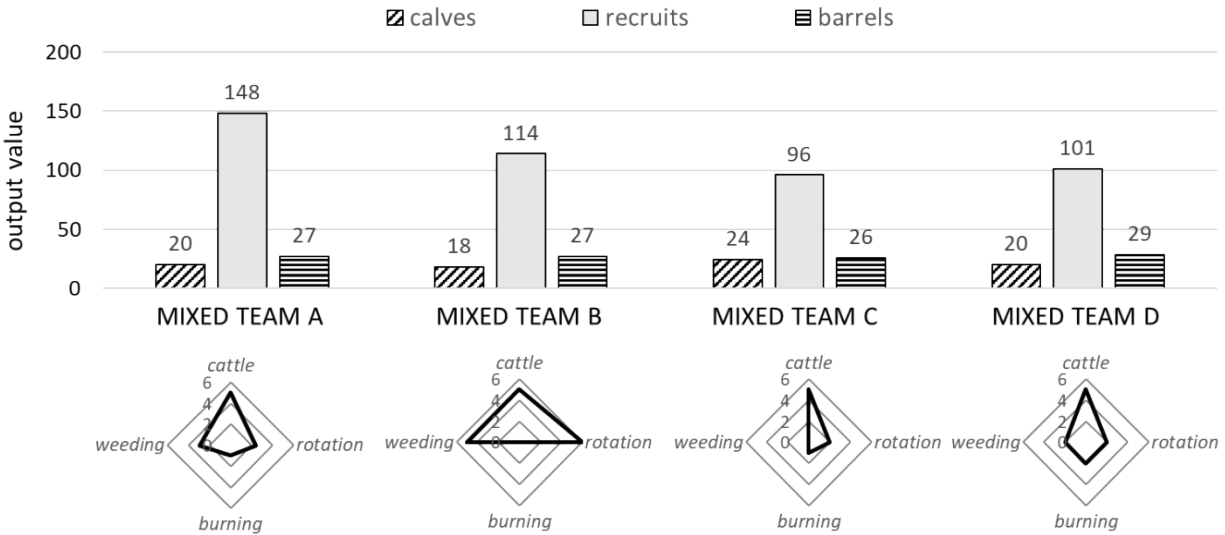
### 3.3.5 Reflection meetings

Both groups of farmers considered the simulation exercises increased their awareness of the long-term effects of any current management strategy on resin production and forest cover in the pine savanna, and on the consequences of not paying sufficient attention to recruitment. They also said

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1683 they became more clearly aware of the cattle tradeoff and the need to handle cattle load properly.  
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1685 One farmer summarized it as “I am used to putting any number of cows in my pine stand without  
1686 much thought and take them out when the grass becomes too short, but with no consideration for  
1687 pine saplings; now I know managing stocking size can make a difference”. Farmers did not express  
1688 concern for the fact that most teams did not meet all goals set by researchers in either of the free  
1689 exercises; rather, they highlighted the many tradeoffs involved in such challenging multi-goal  
1690 searches. Interestingly some farmers valued specifically TRUE GRASP as a tool with which they  
1691 could experience the connectedness of many inputs and outputs through their joint responses.  
1692 Some also mentioned that they could see very clearly what were the preferences of their team-  
1693 mates and other participants, when faced with management choices and output tradeoffs. Many  
1694 farmers stated that the ABM sufficiently captures what goes on in the pine savanna and that trying  
1695 to meet goals really made them get involved; that they had fun and paid attention to the behavior  
1696 of the many factors involved, and therefore learned much more than by sleeping over a long tedious  
1697 power-point. External actors valued tradeoff analysis, but some were concerned with the model  
1698 not being sufficiently realistic (e.g. not having slope effects, soil erosion) nor being quantitatively  
1699 predictive (e.g. exactly how many saplings would be produced in real life, and management cost-  
1700 effectiveness).  
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### 1711 *3.3.6 Multi-actor joint ABM exploration*

1712 During the last workshop, all multi-actor teams used a suite of different options (with different  
1713 frequency) rather than focusing on a single one (**Fig. 14**). Interestingly, when trying to define a  
1714 winning team, all concluded that it was not possible nor reasonable as some were ahead in some  
1715 variables, while behind in others, an experience which made the concept of tradeoff even clearer  
1716 to participants. Recruitment-wise, a winner team did stand out; the farmer said about their scores:  
1717 “these resin tanks are our present, these recruits are our future, and these few calves are the tradeoff  
1718 for taking the future into account”.  
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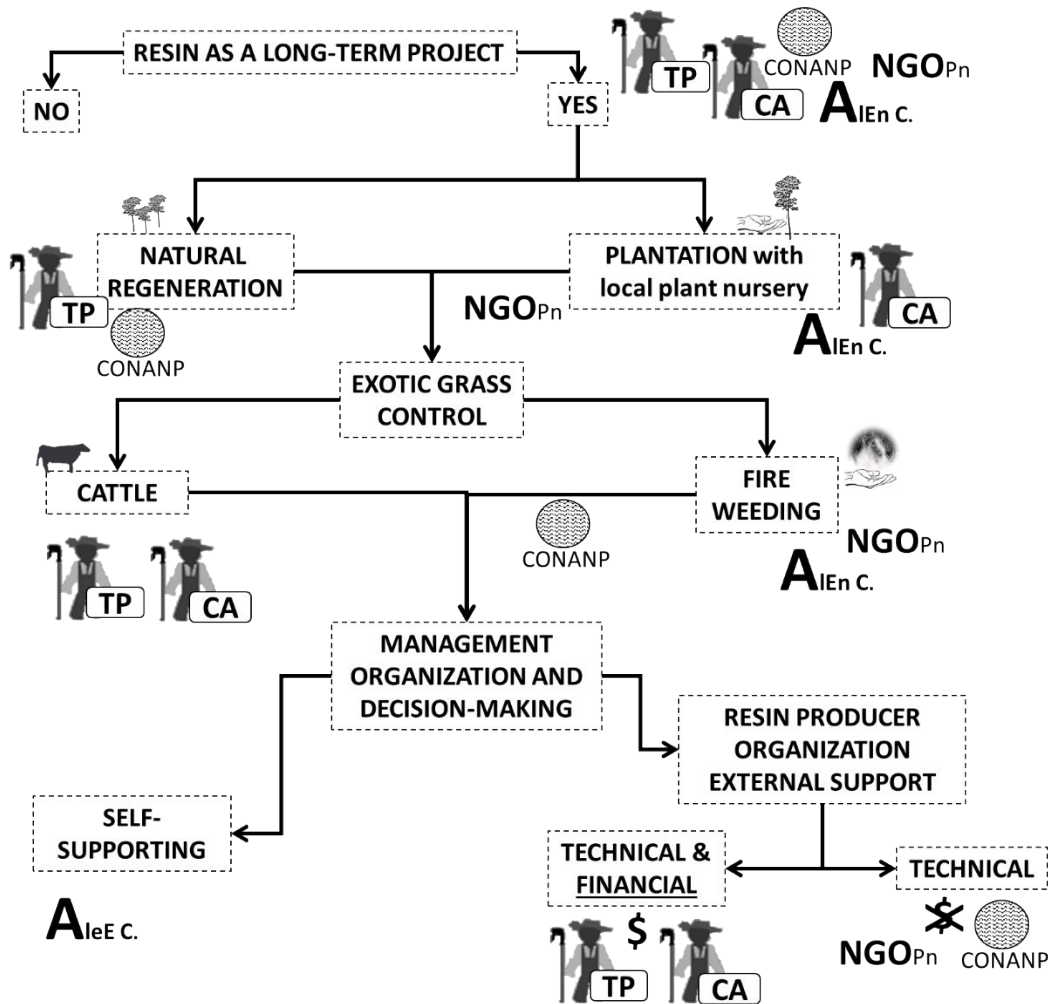


**Fig. 14** Examples of the multi-actor exploration of selected management strategies (radar chart) for cattle loads, rotation frequency, number of burnings and weeding events and their multivariable outputs (bar charts) for the number of recruits, calves and resin barrel production after a 15-years simulation. Teams (x-axis below bar chart) were mixed groups of farmers and external actors.

### 3.3.7 Multi-actor meeting to discuss decision tree

Immediately after the simulation contest, we conducted an exercise for actors to make hypothetical management choices along a decision tree, revealed to them step by step (**Fig. 15**). All chose resin production as a long-term project (> 50 years). The most consolidated production partners (*ejido* California and AIEn Co.) preferred tree stand regeneration with pine nurseries and sapling planting, something they sustained since the pre-simulation interviews (**Fig 9**), while all others preferred assisted natural recruitment. Both *ejidos* preferred exotic grass control around sapling by cattle and suppress fire, while the NGO and AIEn Co. preferred weeding and controlled ground-burning. Some, but not all participants changed their points of view along the process, and particularly after the collective exercise. CONANP had strongly advocated concentrating cattle in intensive land use areas and keeping them out of the savanna; it now accepts it is sound and less costly to control exotic grass with a combination of cattle grazing and controlled fire (and occasionally other methods). The AIEn officer initially stated that cattle were the cause of exotic grass invasion; during the simulations he acknowledged the capacity of cattle to control these grasses and favor recruitment; during the decision-making exercise, he again dismissed cattle presence in the pine savanna. AIEn Co. considered that proper management of pine stands (and

associated monetary costs) to promote new trees should be each farmer's endeavor. The *ejidos* preferred to request government subsidies for such practices through a resin producer organization, while CONANP and the NGO did not favor subsidy requests.



**Fig. 15.** Result of the decision tree exercise in the multi-actor workshop, participants were local resin and cattle farmers from the *ejidos* Tres Picos (TP) and California (CA), resin buyer A|En C., CONANP, and a regional conservation NGO Pronatura. Note, if an actor has no clear position to a question he was placed between both answers (e.g. exotic grass control in case of CONANP).

#### 4 Discussion and Conclusion

Peasant populations established at tropical and subtropical forest frontiers have secularly developed silvo-pastoral practices, livelihoods and landscapes in their territories (García-Barrios and González-Espinosa 2017; Koning, 2014; Sloan, 2007; Van Vliet et al., 2012; Walker et al.,

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2002). Many of their multiple-use forested areas have recently been claimed by other actors and declared MABR. The few new opportunities and the many constraints to silvopastoral use and management dictated by external actors have frequently led to all types and levels of conflict, and lack of success for all parties (Bernard et al., 2014; Bouamrane et al., 2016; Cortina-Villar et al., 2012; Ma et al., 2009; Martín-López et al., 2011). In consequence, actors in some cases have slowly acknowledged the need to engage in collective learning and deliberation to better understand and negotiate their interests. Socio-ecological researchers have shown interest in these processes and are active in helping to develop and deploy strategies, methods and tools to support learning, negotiation and decision making (Berthet et al., 2016; Etienne et al., 2011; Kok, 2009; Mathevet et al., 2011; Tenza et al., 2017; Villamor et al., 2014; Voinov and Bousquet, 2010; Wittmer et al., 2006). These multi-actor efforts are riddled with theoretical and practical challenges related to the different values, knowledge frameworks, interests and power relations of those involved (Galafassi et al., 2017; Huntington, 2000; Tenza et al., 2017). A number of participatory decision-making frameworks have been developed to deal with these challenges (for a review, see Lynam et al. 2007). Additionally, land under silvopastoral use exhibits complex non-linear social and ecological interactions that confer both obvious and subtle tradeoffs, which not only have short-term consequences, but can lead to long-term undesired shifts in vegetation regime, and to local production and livelihood collapse (Allen and Gunderson, 2011; Carpenter and Gunderson, 2001; Filatova et al., 2016; Filatova and Polhill, 2012). ABMs and RPGs are instruments well suited to capture and explore in stylized and dynamical form these complex silvopastoral behaviors (An, 2012; Becu et al., 2008; Bousquet et al., 2002; Etienne, 2014; Filatova et al., 2016, 2013; Parker et al., 2003; Villamor and van Noordwijk, 2011; Voinov and Bousquet, 2010). A small but growing suite of rangeland and silvopastoral tools have been developed: SYLVOPAST (Etienne, 2003), SIERRA SPRINGS (García-Barrios et al., 2011, 2015), ABM/RPG grazing tool for herders and foresters (Dumrongrojwatthana et al., 2011), RANGELAND RUMMY (Farrie et al., 2014), SEQUIA BASALTO (Bommel et al., 2014), GRAZING GAME (Villamor and Badmos, 2015), FORAGE RUMMY (Martin, 2015), and KULAYIJANA (Perrotton et al., 2017). They differ in their specific purposes, complexity, precision and realism and in actors' involvement in the various stages of development. Creating an ABM-supported RPG that represents the dynamics of silvopastoral land subject to a suite of management options and actors' interests is in itself a very elaborate process that involves dealing with many design tradeoffs and difficult choices regarding

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realism, precision and generality. We and others have previously found that smallholder farmers - in some but not all senses - are initially in disadvantage relative to other actors when learning, using and interpreting these complex tools, but that the gap can be closed (Garcia-Barrios et al., 2017). Thus, we consider that design decisions should be led by making sure that smallholder farmers can engage, trust the qualitative outcomes, enjoy the virtual immersion in complex behaviors, and contribute to the collective learning experience (Galafassi et al., 2017; Garcia-Barrios et al., 2017; 2015; 2011; Le Page and Perrotton, 2017; Perrotton et al., 2017).

The tool described in this paper allows exploring management options and assessing their consequences in the short- (10-15 years) and mid- (16-50 years) term. Each combination of options is investigated independently. The tool is therefore currently suitable to explore individual management options at the farm level or to represent landscape effects, assuming that a collective agreement for centralized management exists. Yet the ABM would need to be further developed in order to capture more complex social behaviors, where defection and free riding may exist, and where individual agents are making concurrent decisions accounting for what the others may decide at the same time. The consequences on the landscape could differ significantly from centralized management. Such a model (which could be built in NetLogo's Hubnet platform) would offer a group of 5-6 participants the possibility to re-adjust their individual management options at each step during a simulation run. This would allow going further than the "two-brothers" experiment into co-managing renewable resources. In short, there is ample space for further developing the model.

We will now briefly discuss the most relevant findings derived from pre-modelling interviews, model building, pre-workshop quizzes, interactive simulation workshops and group deliberations.

#### *Pre-modelling interviews*

Most smallholder farmers stated that (a) resin as an income option will grow in the future and that they are willing to conserve the pine-oak savanna; (b) sapling establishment requires bare soil, and is reduced by dense exotic grass cover, pine-leaf litter accumulation and sapling trampling by cows; (c) grazing is one of several possible means for pine recruitment, very few mentioned fire management to burn the grass. This recent fire taboo (or silence) stems from previous conflict with CONANP over traditional fire use in the area (Braasch et al., 2017; Guevara-Hernández et al., 2013; Navarro et al., 2017). Smallholder farmers strongly depend on their ecological knowledge



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but also incorporate information from external actors (Soto-Pinto et al., 2007; Valencia et al., 2015). There is no unique truth, processes change continuously and unpredictably and therefore knowledge is never complete. Participatory approaches can help navigate such complexity by combining farmer and academic knowledge, and developing together new insights (Allen and Gunderson, 2011; Dawoe et al., 2012; García-Barrios et al. 2017; Vandermeer and Perfecto 2013).

### *Model development and validity*

Structuring and parameterizing TRUE GRASP based on quantitative and qualitative knowledge provided by farmers, field research and literature was successful. This simulation framework exhibits sufficient internal validity, because - as shown by a thorough sensitivity analysis - (a) it reproduces qualitatively the different long-term scenarios of interest for pine recruitment (closed pine forest, open grassland and pine savanna); (b) it produces qualitative scenarios that are robust under various combinations of management practices (cattle, rotation, weeding, fire), but may shift when ecological thresholds are crossed; (c) it exhibits interesting and credible nonlinear responses to each practice's range of possible values as well as credible nonlinear tradeoffs among practices and among desired outputs; (d) it clearly captures the fact that similar output syndromes (sets of relevant output values) can be achieved with different management combinations. As reported by An (2012), ABM are increasingly used to simulate the complexity of SES, because they can deal with heterogeneity, featuring feedbacks, nonlinearities and adaptation. They provide several advantages over other models when dealing with land cover change, regime shifts and tradeoffs (Filatova et al., 2016; Miyasaka et al., 2017; Parker et al., 2003).

### *Pre-simulation Quizzes*

TRUE GRASP directly exposes users to nonlinear, non-trivial tradeoffs when using different management practices. Such tradeoffs became apparent to all actors only after having solved the quizzes. Smallholder farmers were more interested in managing cattle tradeoffs, while external actors in managing fire tradeoffs, again manifesting their respective biases and preference taboos. It is ironic, considering that a few years ago smallholder farmers used fire liberally and externals prohibited it. As described in Galafassi et al. (2017), these outputs can be explained in three ways; a) tradeoffs are often invisible, because of a lack of systemic understanding; b) tradeoffs are perceived differently by different actors; different people see gains and losses differently; and c)

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2019 tradeoffs are often hidden or ignored, when taboos are involved (Daw et al., 2015; Schoemaker  
2020 and Tetlock, 2012).

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2023 *Learning, trusting and using TRUE GRASP*

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2025 All actors found the long-term qualitative forest cover scenarios relevant and credible, appreciated  
2026 this long-term approach to management choices, and increasingly trusted the tool for qualitatively  
2027 exploring ranges and combinations of management options and their tradeoffs. Most users  
2028 correctly predicted the qualitative forest cover scenarios, discovered and dealt with tradeoffs, and  
2029 found their way towards the goals for cattle production, pine stand persistence, and resin  
2030 production pre-established by researchers as training exercises. As mentioned earlier, TRUE  
2031 GRASP behaviors and outputs are only qualitatively predictive. Sun et al. (2016) called these kinds  
2032 of qualitative models simple ABMs, and Le Page and Perrotton (2017) call them stylized, referring  
2033 to the model structure as compared to quantitative, data-hungry prediction models. Generic,  
2034 stylized qualitative models are highly recommended for participative approaches to foster  
2035 deliberation and decision making (Edmonds and Moss, 2004; Le Page and Perrotton, 2017; Sun et  
2036 al., 2016; Tenza et al., 2017; Voinov and Bousquet, 2010), especially when dealing with tradeoffs,  
2037 hard choices between ecological and social benefits, individual and community benefits, and  
2038 among actors who bear different costs and benefits (Lazos-Chavero et al., 2016). Interestingly, the  
2039 reserve management team expected an ABM with more realism and prediction of operational  
2040 quantities, while farmers expressed they were content with experiencing and becoming more aware  
2041 of interactions, tradeoffs, and indirect effects. Thus, the tension between favoring generality,  
2042 realism, and precision (Levins, 1966) and between building theoretical, stylized or realistic ABMs  
2043 (Le Page and Perrotton, 2017) is probably unavoidable in multi-actor settings.

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2049 During these exercises, team members with common goals had clear reasons to collaborate. In the  
2050 “two brothers” exercise performed by farmers, there was room for transforming tradeoff  
2051 management into conflict and dominance of one brother’s goals and interests over the other, yet  
2052 this did not occur. This has at least two explanations or their combination: users would actually  
2053 collaborate in real life in an effort to balance the tradeoffs in a fair way, as found by García-Barrios  
2054 et al. (2015), where users enjoyed exploring the possibility of such collaboration in a safe  
2055 environment, with no significant cost in their real-life relations, as found by Berthet et al., (2016).

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2068 *User’s evaluation of TRUE GRASP*

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Most actors said that the exercises had increased their awareness of (a) the long-term resin production and forest cover effects, (b) the consequences of low pine recruitment, (c) the usefulness of cattle and/or fire to increase pine recruitment, and (d) the many tradeoffs involved. They said that TRUE GRASP really made them get involved in dealing with the relevant issues, have fun and pay attention to the behavior of the many factors involved and their interactions. The capacity of the TRUE GRASP workshops to produce collective socio-ecological learning is in line with other ABM and RPG rural workshops (Berthet et al., 2016; Garcia-Barrios et al., 2017, 2015, 2011; Patel et al., 2007; Perrotton et al., 2017; Speelman et al., 2014a, 2014b; Villamor et al., 2014; Villamor and van Noordwijk, 2011).

### *Multi-actor exercises and deliberation*

Exploration and negotiation among actors ran smoothly and collaboratively (although subtle dominance by external actors was frequently expressed by hoarding the computer mouse and output sheet). These actors have been interacting and negotiating different issues for the past 20 years and the exercise reflected in a playful way both collaboration and unspoken conflict of their past relationships. One principle of RPG described by the ComMod group, but also by other authors (Etienne, 2014; Lynam et al., 2007; Villamor and van Noordwijk, 2011) is the capacity to cross boundaries among actors belonging to different worlds, while being interested in the same resource and to promote a dialog in a fair and balanced multi-actor space.

Fostering the dialog in MABR is essential, because actors would be able to present, discuss and better understand one another's perspectives and needs (Bouamrane et al., 2016). However, it is also important to provide a space for social and collective learning among actors, to solve problems, conflicts and to negotiate agreements (Patel et al., 2007).

While in the TRUE GRASP exercise, participants were more open to combine contrasting management practices, during the decision tree exercise they privileged their previously expressed real-life preferences, while stating they remained open to further discussion. This is not surprising as ABM/RPG workshops should not be expected to produce effects totally aligned with the model's stylized propositions, nor to do so immediately and in a one-shot experience. Yet, we are certain that the simulation exercise leveled the ground for a more honest discussion and for understanding other actors' statements and choices during this last exercise. As mentioned by Bodin (2017), participatory approaches are sometimes unable to deliver immediate and expected

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2131 concrete results, or create the illusion of results in the form of symbolic outcomes such as  
2132 aggregated wish lists, where conflicts of interest are left untouched. The creation of a socially and  
2133 ecologically sustainable management plan implies a fair and balanced designed arena, for  
2134 productive discussions and negotiations between the smallholder farmers and external actors  
2135 (Etienne, 2014; Perrotton et al., 2017). However, this calls for the commitment of researchers and  
2136 all actors to social learning that truly involves smallholder farmers and provides tools that do not  
2137 overwhelm them (Galafassi et al., 2017; Garcia-Barrios et al., 2017).  
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# Appendix A

## Supplementary data

### **TRUE GRASP: Actors visualize and explore hidden limitations of an apparent win-win land management strategy in a MAB Reserve**

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### **TRUE GRASP: Overview, Design concepts, and Details (ODD)**

The following description of the TRUE GRASP model follows the updated ODD (Overview, Design, and Details) protocol by Grimm et al. (2010). Some sections of the description were adapted to address socio-ecological contexts involving a human decision making process, as recommended by Müller et al. (2013).

## **1. Overview**

### *1.1 Purpose*

TRUE GRASP (Tree Recruitment Under Exotic GRAsses in a Savanna-Pineland) is a socio-ecological agent-based model (ABM) and role playing game (RPG) for smallholder farmers and other stakeholders involved in rural landscape planning. This model, which simulates economic and ecological tradeoffs and can be used in participatory decision-making processes, addresses long-term consequences of current land use practices - such as changes in land cover and regime shifts, and identifies tipping points and thresholds.

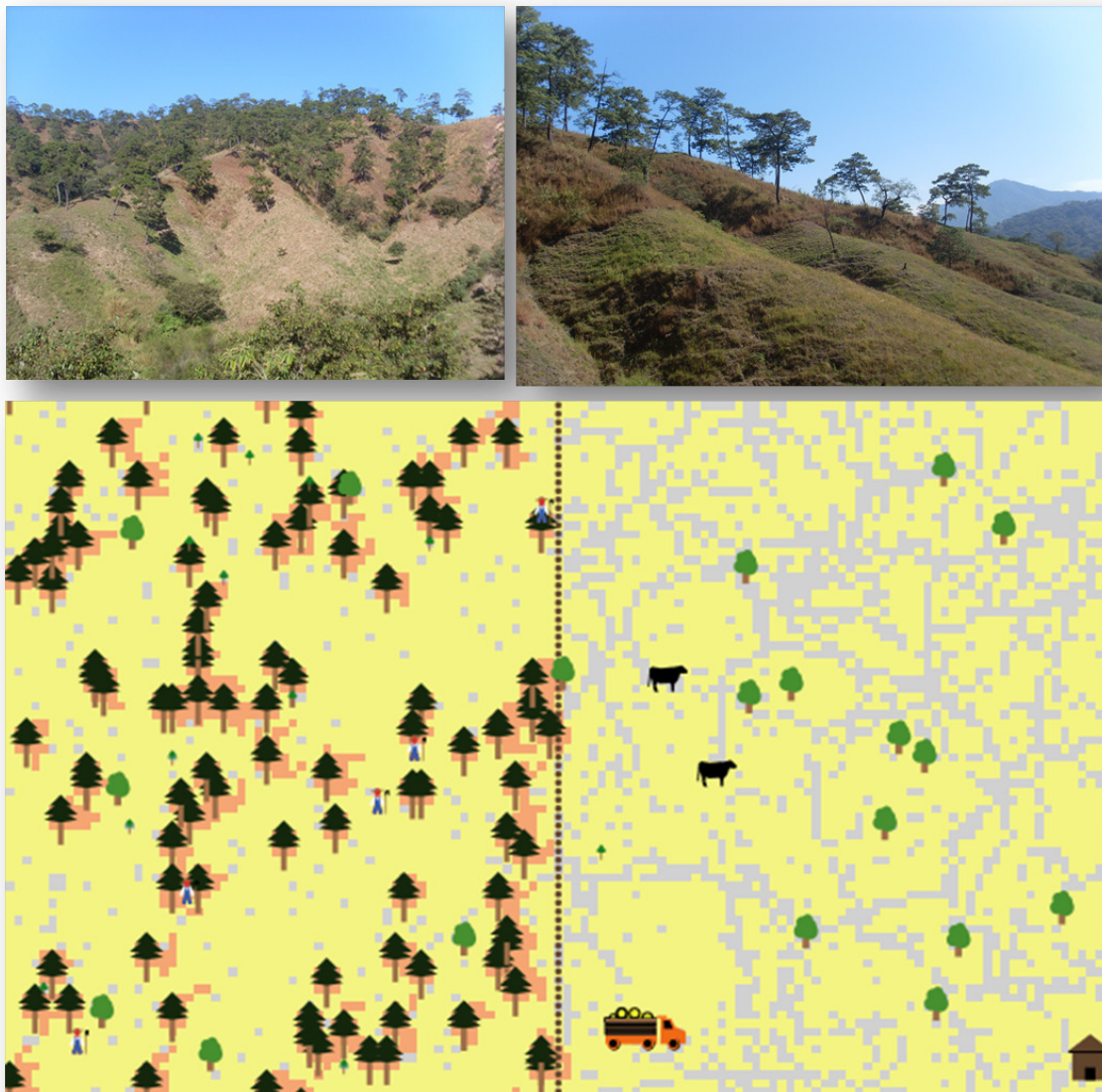
Design of TRUE GRASP is based on 3 years of socio-ecological fieldwork in a human-induced pine savanna in La Sepultura Biosphere Reserve (SBR) in the Mexican state of Chiapas. In this savanna, farmers harvest resin from *Pinus oocarpa*, which is used to produce turpentine and other products. However, long term persistence of this activity is jeopardized by low tree recruitment due to exotic tall grass cover in the forest understory (see Braasch et al., 2017). The TRUE GRASP model provides the user with different management strategies for controlling exotic grass cover



and avoiding possible regime shifts, which in the case of the SBR would jeopardize resin harvesting.

### *1.2 Entities, state, variables, and scales*

The virtual world of the model consists of 81 x 129 cells, which together represent a 4-hectare plot of land; each plot in the model consists of 2 hectares of open pasture and 2 hectares of pine savanna, representing typical landscapes in the SBR (Fig. 1).

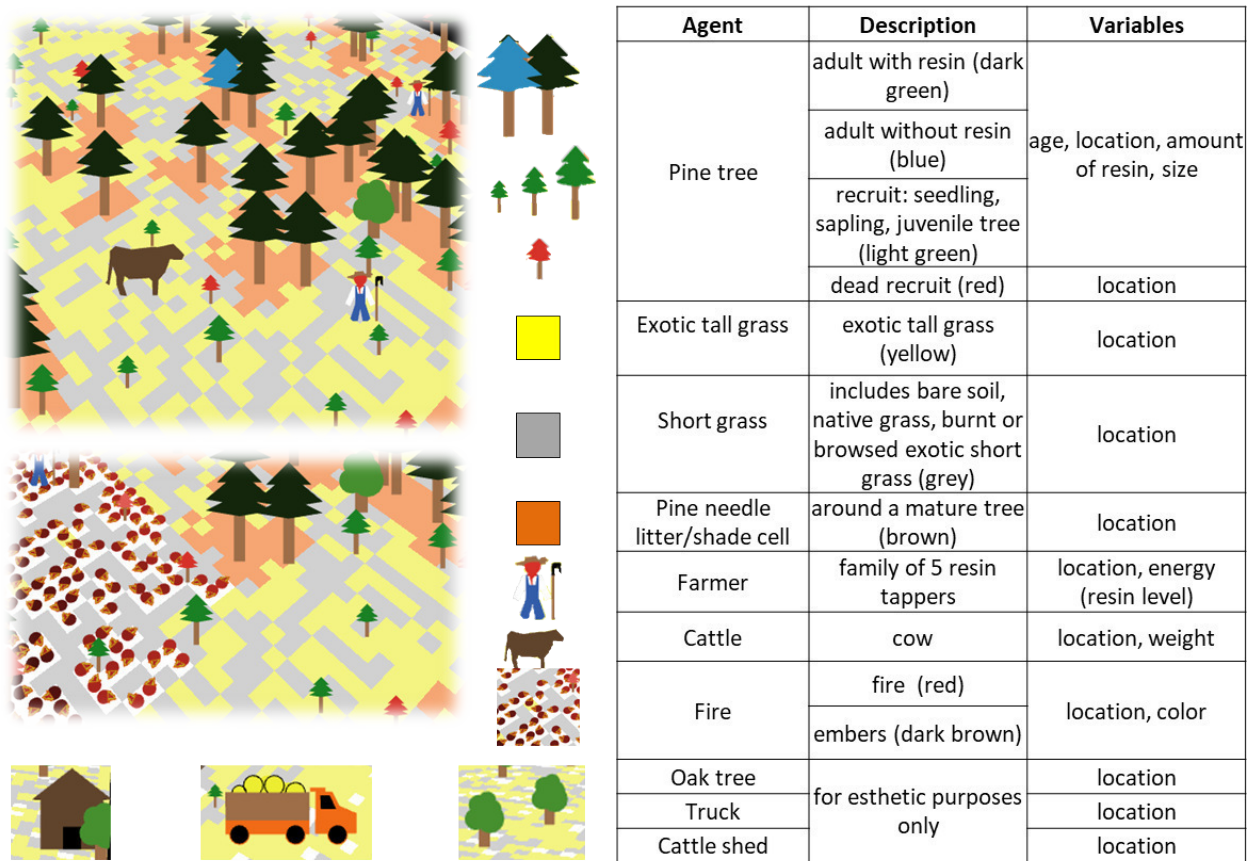


**Fig. 1** Design of the virtual world based on a mountainous landscape in La Sepultura Biosphere Reserve, Chiapas, Mexico, representing 2 ha pine savanna and 2 ha open pasture.

The savanna of the virtual world contains 100 adult pine trees, whose geographical position is defined in the model. Mature trees produce resin, shade, leaf litter, and seeds. Seeds germinate and resulting recruits pass through four stages (seedling, sapling, juvenile, and adult) which vary by age and size. Farmers in the model collect resin from adult trees, and deposit it in their resin container. Each tree in the model has a defined amount of resin, which decreases upon tapping. This is represented by the tree's resin tank. If a tree's resin tank is empty, the tree may be used for timber production. If the user does not select timber production as a management practice, as long as the tree is not cut down, it survives until 140 years. Understory vegetation consists of: a) Short grass cells (native grass cover, bare soil, browsed or burnt exotic grasses— all of which are inedible to cattle), b) exotic tall grass cells, and c) areas of pine needle litter which are impacted by the shade of adult trees. The geographic location of these cells is specified by their coordinates (Fig. 2). Within the virtual pine savanna, five farmers move in a semi-random walk in search of adult pine trees for resin tapping and harvesting, using the “Mushroom Hunter” model algorithm by Railsback and Grimm, (2012). The amount of resin a farmer harvests is recorded in his resin container, which represents his energy. This amount increases as resin is harvested and decreases as the farmer moves and energy is lost. If a farmer's energy reaches zero, the farmer “dies” - that is, he stops harvesting resin. When a farmer's resin container becomes full, the resin is stored in 200 kg barrels for sale. Farmers' movement is recorded using geographical coordinates. Cows also move in a semi-random walk in the virtual world, using the “Rabbits Grass Weeds” model algorithm by Wilensky, (2001). They eat grass and their movement is also specified via coordinates. As they roam, they use up energy, and as they eat grass, they gain energy. If a cow has a surplus of energy at the end of the year, it reproduces one calf. If energy reaches zero, the cow dies. Another element in the system is fire, which may be manually induced or occur randomly with a 4 % annual probability. Fires are shown in red to denote flames and brown to denote embers, following the “Fire Percolation” model by Wilensky (1997). Fire converts exotic tall grass cells and leaf litter (both of which are considered to be fuel) into short grass (burnt) cells. If a recruit (< 9 yr.) grows in a “fuel” cell, it dies.

The principal external controls of the model, which are set by the user, are cattle load (number of cows), cattle management strategy (taking into account only one or both sites), frequency of rotation, manual weeding, and controlled burning.

One iteration (time step) represents one day in the virtual world. The user defines which of three scenarios the model will simulate: short-term (<10-years), mid-term (10-30 years), or long-term (>50 years). The eastern and western borders of the virtual toroid world are impermeable, while those to the north and south are permeable. If a mobile agent (farmer, cow, fire, or seed) crosses a border, it re-enters on the opposing border of the virtual world in the same vegetation category (from savanna to savanna, or from pasture to pasture). In order for the model to appear more realistic - especially to rural farmers, it includes oak trees, a resin-transporting truck, and a cattle-shed, which have no effect on any of the agents and are not involved in any processes (Fig. 2).



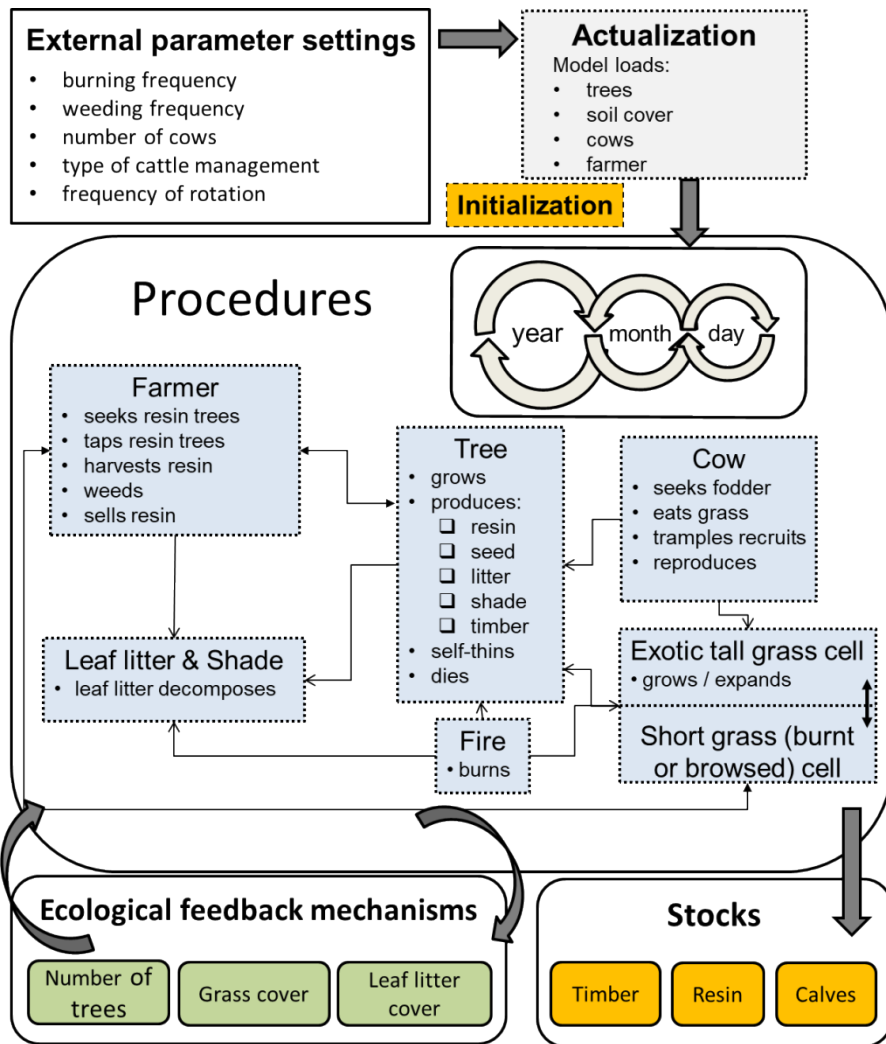
**Fig. 2** Left: three-dimensional view of the TRUE GRASP model, showing all agents involved. Right: description of agents and their controlling variables.

### *1.3 Process overview and scheduling*

Fig. 3 presents an overview of all interactions among agents and processes involved in the model during simulation. Before beginning the simulation, the user chooses among a set of management strategies for controlling exotic grass cover; these strategies vary by initial cattle load and management system, rotation, weeding, and burning frequency. After actualization, the model loads pine trees, vegetation cover, cows, and resin-tapping farmers. Upon running the model, several sub-models and processes operate sequential:

- a) Mature trees produce shade, litter, resin, seeds, and wood, and later die.
- b) Young trees become established and grow, and older trees eliminate some seedlings, thereby regulating their density through a self- thinning process.
- c) Exotic tall grass cover expands and regrows after burning or being consumed by cows.
- d) Leaf litter accumulates around mature trees, and when a tree dies and leaf litter below it decomposes, these cells are converted into short grass cells.
- e) Famers move, seek resinous trees, tap them, and harvest resin; if the user selects weeding, farmers weed around mature resinous trees.
- f) Cows move to seek fodder, eat grass, trample recruits under age 3, and reproduce.
- g) Fire burns grass, leaf litter, and recruits under age 9, if they become established in a “fuel” cell.

In the model, each ecological process is cyclical, as in the real world. Tree growth, weeding, and resin tapping are simulated in a daily time step; rotation and resin selling are simulated monthly; and seed production, calf reproduction, and burning are simulated annually. All agents interact directly or indirectly with other agents and with the environment. These interactions establish a system of feedback mechanisms in which the state of the agent, its variables, and their quantity continually change. The model records resin barrels, timber, and calves as stocks leaving the system (Fig. 3). The procedures mentioned above are described in detail below in the section on sub-models.



**Fig. 3.** Flowchart of the principal processes involved in the model. Direct interactions between agents are denoted with arrows.

## 2. Design concepts

TRUE GRASP was created for educational purposes, rural land use planning, and as a participatory research tool. One purpose of this model is to allow actors to explore the individual and combined effects - as well as tradeoffs - of three methods of controlling exotic grasses in pine savannas: fire, weeding, and grazing cattle.

Design of the model, selection of agents, definition of variables, and parameterization were based on a 3-year participatory socio-ecological study (2014 to 2016) in the *ejidos* (mix of private and collectively-owned land holdings) California and Tres Picos in La Sepultura Biosphere Reserve,

in Chiapas, Mexico. The objective of the study was to identify processes affecting natural recruitment of the resinous pine *P. oocarpa*. Two principal impediments to natural regeneration were identified: a) presence of two highly competitive exotic grasses (*Melinis minutiflora* and *Hyparrhenia rufa*), and b) a 20-year history of fire suppression as a strategy for conserving the biosphere reserve's forest. We then tested the hypothesis that controlled extensive cattle grazing favors tree regeneration and reduces risk of fire, thereby contributing to maintaining the ecologically unstable - but socially desirable - structure of the pine savanna system, in which exotic grasses are dominant (see Braasch et al., 2017). Use of cattle to promote tree regeneration was mentioned by local smallholder farmers, and has been described in the literature as a disturbance-based method of maintaining a balance between tree cover and grass cover in savanna ecosystems (Coppock et al., 2017; Fuhlendorf et al., 2009; Limb et al., 2011; Murphy and Bowman, 2012; Van Langevelde et al., 2003). Herbivory reduces competition of grass with trees, thereby favoring tree recruitment and growth (Werner, 2005). However, cattle must be carefully managed as they have a strongly negative effect on recruits due to trampling and browsing (Braasch et al., 2017).

Decision-making: The farmer agents in TRUE GRASP set off very simple environmental feedback processes. They are not autonomous, as they are controlled by decisions made by real human participants. TRUE GRASP lies somewhere between a very stylized ABM and a very elaborate RPG. Upon playing the game, users learn through feedback provided by the model's variables. In order to improve the outcome, the results are analyzed, adjustments are made in management, and the simulation is repeated. New initial conditions for the following model run are set also based on real life experience, desired landscape cover, and land use interests (livestock production, resin extraction, timber, and conservation).

Emergence: Depending on the management strategy selected (grazing, weeding, and controlled burning - or a combination of these), various ecological processes emerge which affect long-term land cover. In the long term, the structure of the savanna may persist, or the system may transition to alternate regimes such as closed pine forest or open pasture, directly impacting future land use and farmers' livelihoods.

Adaptation: Agents in the model react to changing conditions. For example: a) If resinous trees are scarce and resin production declines, farmers abandon the activity and leave the system; b) Lack of grass cover due to overgrazing affects the annual calf production rate, and in the long term,

adult cows die: and c) The amount of fuel available determines how many recruits die as a result of fire and regulates tree species' population growth.

*Uncertainty:* The TRUE GRASP model provides the user with a set of problematic or uncertain conditions: a) When controlled burning is not used as a management strategy, annual risk of a human-induced or natural forest fire is 4%; b) Whether or not a recruit under age 9 is burned depends on the amount of fuel and the connectivity among fuel cells at the moment of burning, which is not predictable; and c) The short-term economic benefit as a result of present management may be counteracted by a regime shift in the long run as a result of the management strategy selected; however, at the start of the simulation, some long term tradeoffs are often not visible or are ignored by the user.

*Collectives:* A single exotic tall grass cell inhibits seed germination, but the set of these exotic tall grass cells also has an effect on recruits. Recruits growth rate is inhibited in proportion to the number of surrounding exotic tall grass cells. A continuous soil cover of fuel consisting of exotic tall grass cells and pine needle litter also affects fire expansion and mortality of recruits. Also, if tree density increases, leaf litter and shade produced by mature trees form a continuous soil cover that suppresses regrowth of exotic grass as well as establishment of seedlings.

*Prediction:* The model contains a set of output variables that may be used to predict - for example - number of recruits, future tree density, grass cover for calf production, and number of trees available for long term resin production.

*Learning:* TRUE GRASP fosters collective social learning, as it is an RPG. When the game is played, the model effectively creates feedback loops between the virtual and real worlds. As the user learns by doing, he or she may repeatedly explore different combinations of management strategies to control the highly competitive exotic grass cover and discover the tradeoffs of each management strategy.

*Observations:* In order to observe and analyze tradeoffs, the model provides monitors and graphs showing the most relevant economic and ecological output variables: number of resin-producing trees and recruits (live, trampled, burned, and self-thinned); exotic tall grass, short grass (burnt or browsed), and litter and shade cells; and stock for producing calves, resin, and wood.



*Interactions:* Continual direct and indirect interaction of most agents results in a set of tradeoffs. For example, with respect to the interaction of cows, recruits, grass cover, and fire, fire and cattle trampling have a direct negative effect on recruits, while grazing has an indirect positive effect, reducing highly competitive exotic grass cover and thereby favoring seedling establishment and growth. This reduction in continuous fuel cover also reduces spatial expansion of fire.

*Stochasticity:* Many of the processes in the model are cyclical, such as seed and litter production. However, number and distribution of seeds is random. Furthermore, if controlled fires are not carried out, annual risk of fire is 4 %.

### **3. Details**

#### *3.1 Implementation details*

The model was implemented using the NetLogo platform, version 5.2.1. (Wilensky, 1999), available upon request by e-mail to the first or second author of this paper. Development of the model consisted of four phases: a) design and parameterization based on a three-year long socio-ecological study, b) 12 scholars testing the model in order to evaluate ecological processes, c) 10 smallholder farmers playing the game separately to evaluate ease of comprehension and visually improve the model to facilitate use, and finally d) a total of 10 students, foresters, and scholars testing the model and playing the game in order to define game rules for later use in a participatory multi-actor workshop. After each phase, a variety of sensitivity analyses were conducted, and the model's visual design and source code were modified based on users' recommendations.

#### *3.2 Initialization*

The initial condition of the model represents the start of the resin tapping activity in the savanna. The model, which shows ecological conditions similar to those in La Sepultura Biosphere Reserve, simulates possible future land-cover changes in a daily time step. Each time the model is run, it begins with 100 mature resinous trees, in similar densities as in the real world. The trees, which range in age from 80 to 130 years, are always located in the same positions; initial resin volume is constant for all trees. Understory vegetation cover is set at a proportion of 90 % exotic tall grass cells to 10% short grass (burnt or browsed) cells. Both vegetation types are randomly distributed



in the virtual world. Leaf litter and shade cells are not present initially, but begin to appear as soon as the model begins to be run. The number of resin tappers is five for all runs, representing a family of five. Number of cows, livestock management strategy, rotation, frequency of burning, and frequency of weeding are chosen by the user.

### ***3.3 Input Data***

No input data were used.

### ***3.4 Sub-models***

This section provides details of all sub-models and procedures listed in Fig. 3, organized into five models: a) pine tree life cycle sub-model, including shade and litter production, b) cow sub-model, c) grass growth sub-model, including exotic tall grass and short grass (burnt or browsed) cells, d) fire sub-model, and e) resin tapper sub-model.

#### ***3.4.1 Pine tree life cycle sub-model***

Each pine tree over the age of 15 annually produces 6 seeds, which are randomly distributed within a 15-cell radius. A seedling may only become established in a short grass (burnt or browsed) cell; litter, shade, and exotic tall grass cells inhibit germination (Fig. 4). During its first 3 years, a tree is susceptible to trampling by cattle. Recruits that die from trampling, fire, or clearing change in color from green to red, and after two years disappear from the virtual world. In order to simulate the ecological effect of decreased growth rate over time due to increased competition by surrounding trees, until age 6 growth rate continually decreases in proportion to the number of surrounding exotic tall grass cells. If a tree less than 9 years old in an exotic tall grass or leaf litter cell - which serve as fuel - is exposed to fire, it will be destroyed. Recruits within a three-cell radius of trees over age 10 die through a self-thinning process. If tree has survived all risks and has reached 10 ecological years (the time required for a tree in an exotic tall grass region to grow the size of a tree that does not face competition), it begins to produce shade and leaf litter. Once pine trees reach the age of 20, they produce resin for 10 to 20 years. If a tree's resin tank is empty, the color of the tree changes from green to blue, and it can be used for timber. Each year, 10 % of all trees without resin are automatically harvested. When the user does not choose wood production and a tree reaches the age of 140, it dies naturally and leaves the system; it is assumed that the

farmer makes use of it. When a tree dies naturally or is used for timber, shade disappears immediately and litter decomposes the following two years, converting the forest floor to short grass cells.

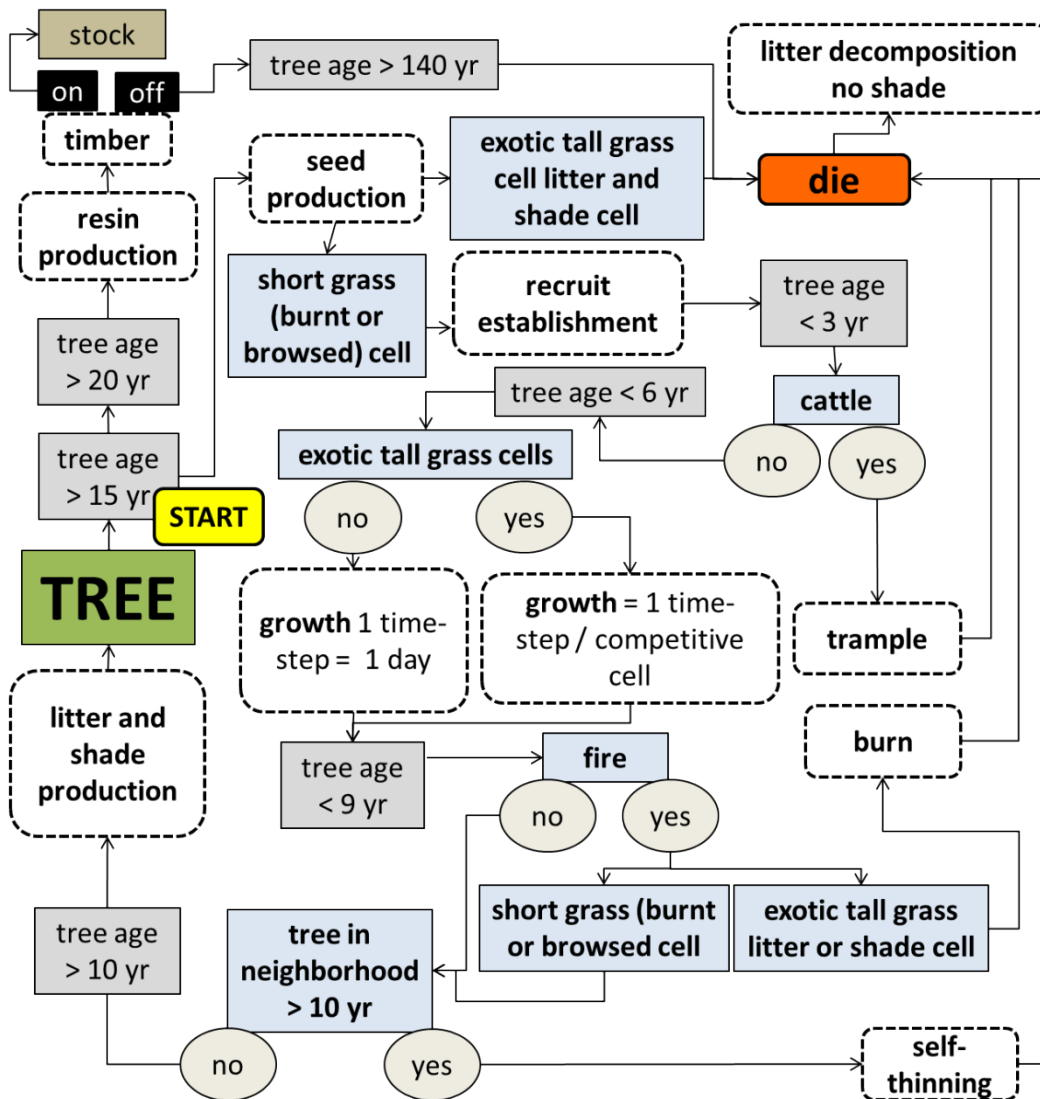


Fig. 4. Flowchart for the pine tree life cycle. The chart is read beginning with the yellow “start” box

### 3.4.2 Cow sub-model

The cow and exotic grass growth sub-model is a modified version of the “Rabbits Grass Weeds” model from the NetLogo library, developed by Wilensky, (2001). We broadened and otherwise modified the source code of this model to adapt it to our purposes.

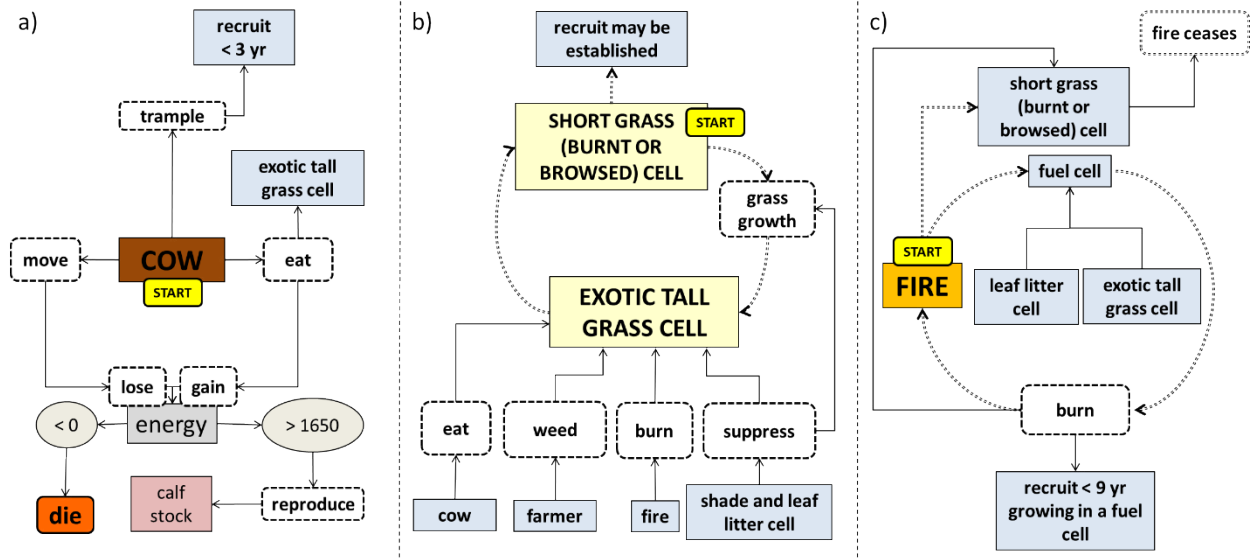
Cattle move randomly within the assigned space: pasture land, savanna, or both - with or without rotation. Upon coming into contact with a susceptible seedling, the cow tramples it and the seedling dies. Each cow has an initial energy level (weight) of 1000 units. Energy is lost each time-step due to movement, and energy increases with consumption of fodder - exotic tall grass. If energy is reduced to zero due to lack of availability of fodder, the cow dies. If sufficient fodder is available and energy surpasses 1650 units - the minimum weight necessary for reproduction, the cow conserves 1000 units for its own maintenance and devotes the surplus (reproductive weight - 1000 units) to producing a calf. Each cow is calibrated to produce no more than one calf per year. Calves do not consume grass, as they are sold and thereby extracted from the virtual world (Fig. 5a).

### *3.4.3 Grass growth sub-model exotic tall grass and short grass cells*

Shade and pine needle litter accumulation suppress exotic tall grass cover and may replace these cells. Exotic tall grass cover may be converted into short grass cells through consumption by cows, burning, or weeding. Short grass (burnt or browsed) cells may be colonized by pine seedlings, but these cells always contain short inedible exotic grass, or at least the established roots of these grasses that have potential to sprout. Over time, a short grass cell may once again be converted into an exotic tall grass cell if it has not been occupied by shade or leaf litter (Fig. 5b).

### *3.4.4 Fire sub-model*

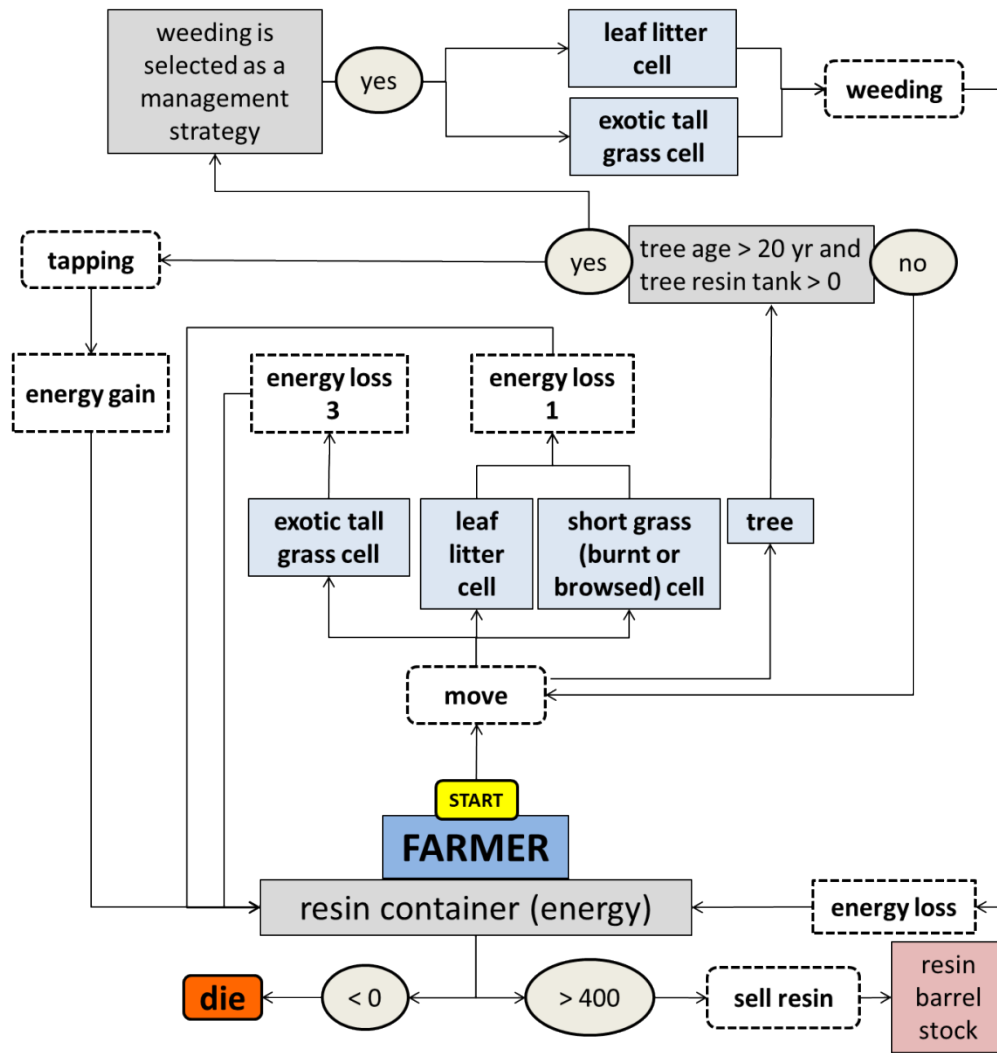
The fire sub-model is a modified version of the “Fire Percolation” model by Wilensky (1997). Spontaneous occurrence of fire has a low probability (4 %). Fire can also be chosen when desired by the user as a management technique, at an established frequency. Fire begins in the center cell of the virtual world, and spreads with each time-step from a burning cell to all (eight) surrounding cells (Moore-neighborhood) covered by fuel (exotic tall grass cells and/or pine needle litter). Fire converts these cells to short grass cells, and any susceptible recruit that has become established in such a cell dies. Mature trees, cattle, and farmers are not directly affected by fire (Fig. 5c).



**Fig. 5** Flowcharts for: a) cow sub-model, b) grass growth sub-model, and c) fire sub-model. The chart is read beginning with the yellow “start” box.

### 3.4.5 Resin tapper sub-model

Each of the five farmers begins with an initial energy level (resin) of 100 units. Farmers move in a semi-random walk throughout the pine savanna in search of resinous trees (Mushroom Hunter model Railsback and Grimm, 2012).. Upon reaching a mature tree ( $> 20$  years) with resin, the farmer taps it and harvests a set amount of resin (15 units). Energy is lost by moving, and gained by harvesting resin. If the energy level reaches zero, the farmer leaves the savanna. If there is a surplus of resin (400 units), harvested resin is accumulated in barrels for sale and leaves the system. The amount of resin sold monthly per tree in the virtual world is similar to that of the real world (40 kg), which is an average of what one family is able to produce on 2 hectares of land containing 100 mature trees. Each farmer moves forward one cell per time-step, walking through short grass (burnt or browsed) cells or leaf litter. If the farmer crosses exotic tall grass cells, he moves 3 times slower, affecting his resin-harvesting efficiency. If the user activates weeding, the farmer in the model converts exotic tall grass cells and leaf litter within a 4-cell radius of a resinous tree into short grass cells. This accelerates the farmer’s forward movement and opens the space for seedling establishment, but also reduces the farmer’s energy level due to labor invested (Fig. 6).



**Fig. 6.** Flowchart for the resin tapper sub-model. Note that energy refers to the farmer’s resin container, which is converted into money that allows the farmer to continue to work. Resin not needed by the farmer for proper working energy accumulates in barrels for sale and leaves the system. The chart is read beginning with the yellow “start” box.



**Fig. 7** Example of tapped resin pines (*Pinus oocarpa*) in the pine savanna. In the real world, bark and wood is scratched away on a weekly basis in order to maintain resin flow into the cup. Each year the cup is moved 50 cm upwards leaving the previous year's. Each face is tapped for 5 years, after which a new tapping face is made on another side of the tree or a new tree is found.

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# Appendix B

## Supplementary data

### **TRUE GRASP: Actors visualize and explore hidden limitations of an apparent win-win land management strategy in a MAB Reserve**

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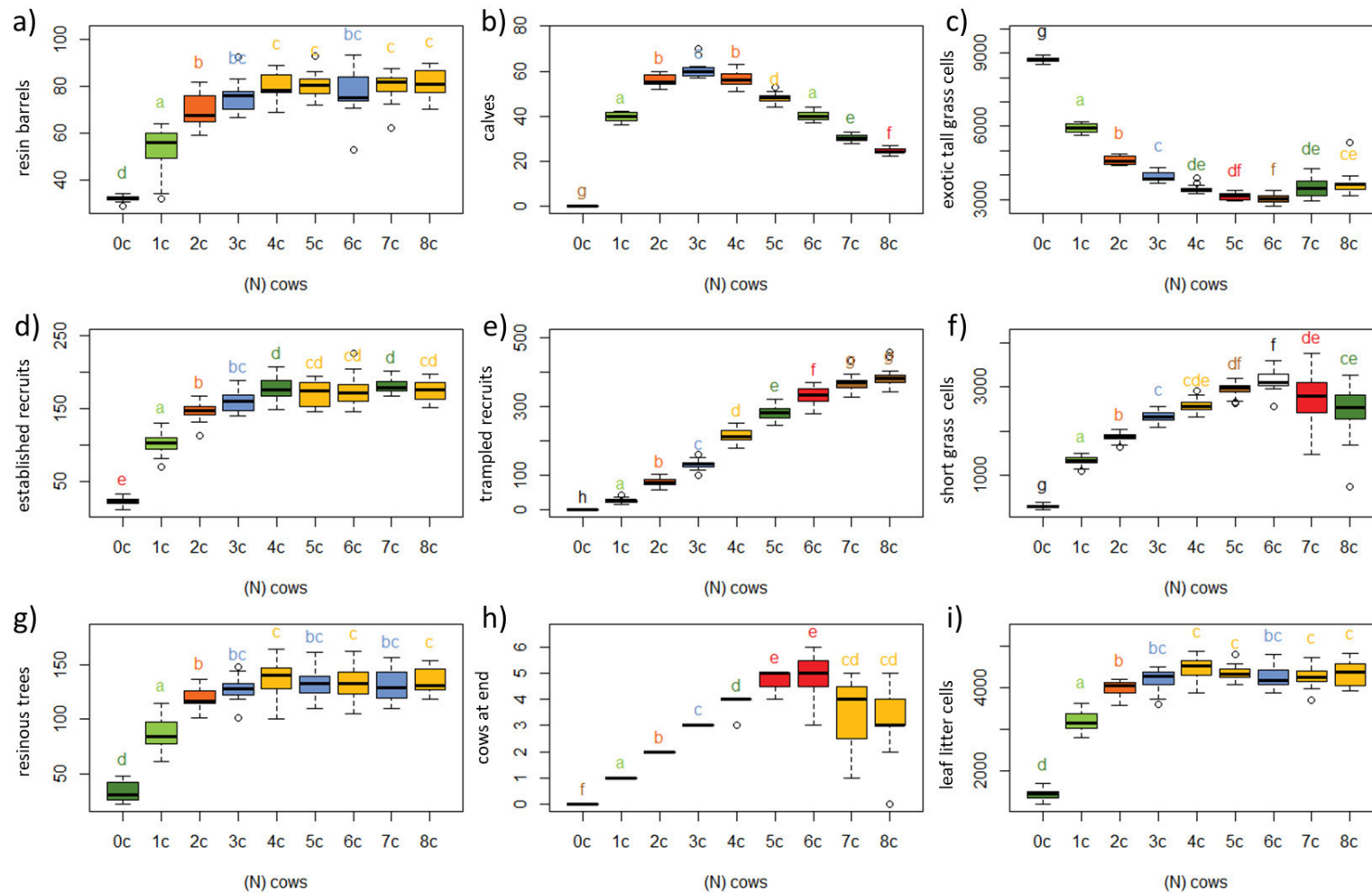
## Sensitivity analysis

Below we present a non-exhaustive though comprehensive multivariate sensitivity analysis of TRUE GRASP'S responses to a set of parameters selected to manage a pine savanna. Also we present a broad spectrum of possible ecological and economic outputs for exercises carried out in a workshop as described in the results section in the main text.



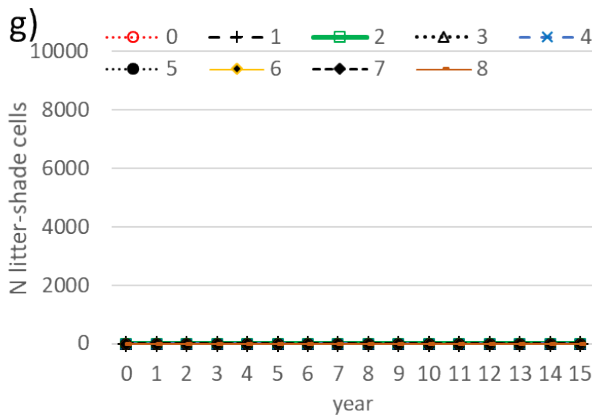
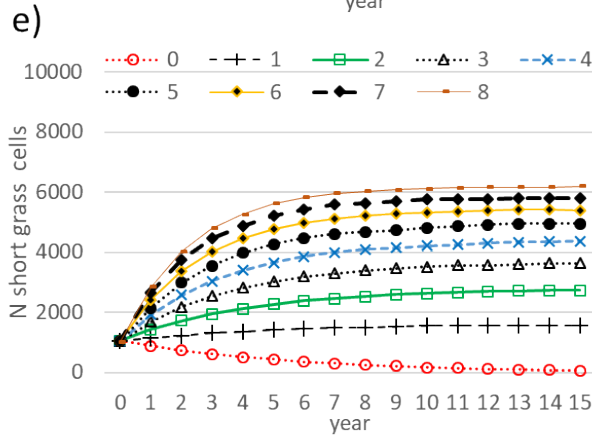
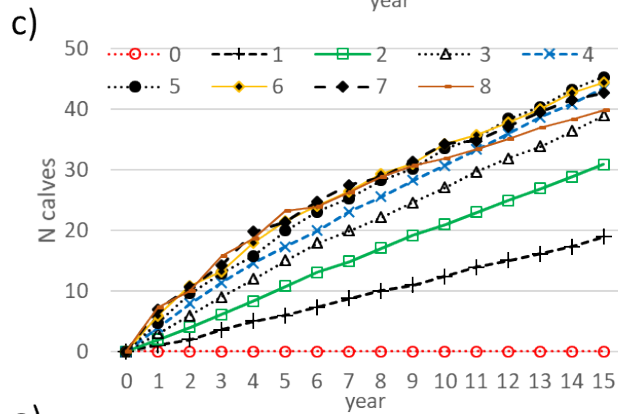
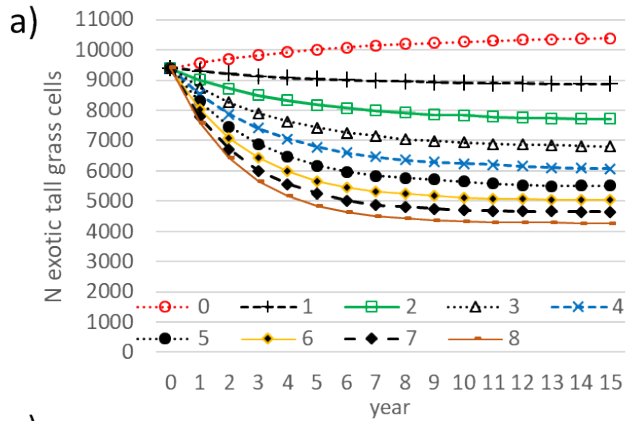
**Table 1.** List of all agents involved in the model, including processes that affect them and output variables

<b>AGENT</b>	<b>PROCESS</b>	<b>EFFECT</b>	<b>OUTPUT VARIABLE (quantity)</b>
ADULT PINE TREE	produces shade and pine leaf litter	pine leaf litter accumulates around tree	pine needle litter and shade cells
	produces seeds	seeds disperse	recruits
	produces resin	resin tapper is attracted	resin
	produces wood	tree dies	timber
	dies	litter decomposes	short grass (burnt or browsed) cells
YOUNG PINE TREE	grows	other seedlings are suppressed (self-thinning)	recruits
	reaches maturity	resin is produced	resin recruits
EXOTIC TALL GRASS CELL	grows /expands	tree recruitment is suppressed	recruits
		tree growth is suppressed	recruits
		resin tapper's movement is reduced	resin (farmers energy)
		cattle weight increases due to grass consumption	calves
	fuel accumulates and burns	recruits die	recruits
		these cells are converted to short grass (burnt) cells	short grass cells
SHORT GRASS (burnt or browsed) CELL	provides open space for seeds	trees may be established	recruits
	no fuel accumulation	recruits survive burning	recruits
LEAF LITTER and SHADE CELL	accumulates around mature trees	exotic tall grass and short grass cells are converted into leaf litter and shade cells	leaf litter and shade cells
		tree recruitment is suppressed	recruits
	fuel accumulates	recruits burn	recruits
COW	moves	cow spends energy	calves
			cows
	tramples	recruits die	recruits
	eats exotic tall grass	cow gains energy	calves
exotic tall grass cells decrease		short grass cells	
RESIN TAPPER (FARMER)	moves	farmer spends energy	resin (farmers energy)
	taps/harvests	farmer gains energy	resin (farmers energy)
	weeds	leaf litter and exotic tall grass cells are converted into short grass cells	recruits
		farmer spends energy	short grass cells
FIRE	burns	fuel cells are converted into short grass (burnt) cells	recruits
		recruits are burned	recruits
		resin tapper moves faster	resin (farmers energy)
		fodder decreases	calves

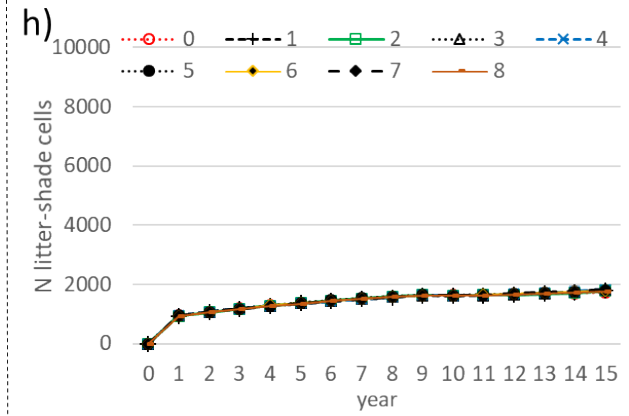
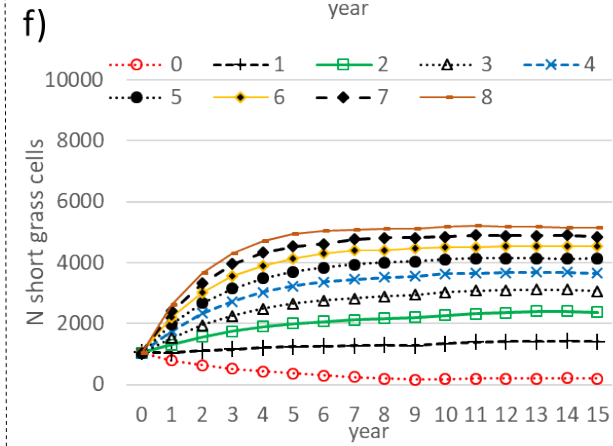
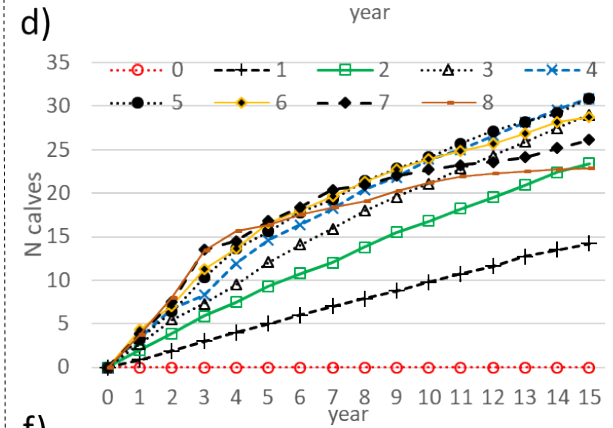
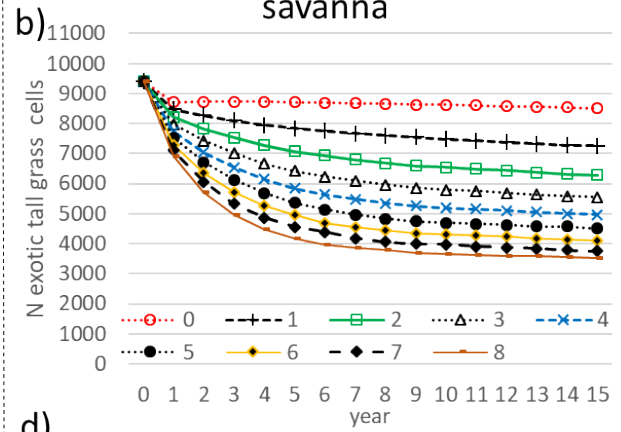


**Fig.1** Long-term (50 year) sensitivity analyses for simulations of different cattle loads (0-8 cows) on 4 ha of land (including pine savanna and open pasture) without rotation. Fire and weeding frequency was set at zero. Each cattle load scenario was run 15 times. Graphs show those economic and ecological output variables which are most relevant to these scenarios: a) resin barrels, b) calves, c) exotic tall grass cells, d) number of established living recruits, e) number of total trampled recruits, f) short grass (burnt or browsed) cells, g) productive resin trees, h) cows at end when simulation was finished, and i) pine needle litter and shade cells. While the majority of the output data increase with higher livestock loads, beyond a 4-cow threshold output stagnates or decreases. Values decrease due to the effect of over-grazing. The model has the capacity of self-regulation less fodder (c) results in less calf production, the cow does not attain the necessary weight for reproduction (b) and in the long run cows are reduced, they die due to scarcity of grass (h). Letters over Box-Whisker plots that share one or more letter label do not differ significantly according to the Tukey HSD multiple mean comparisons test ( $\alpha = 0.05$ ).

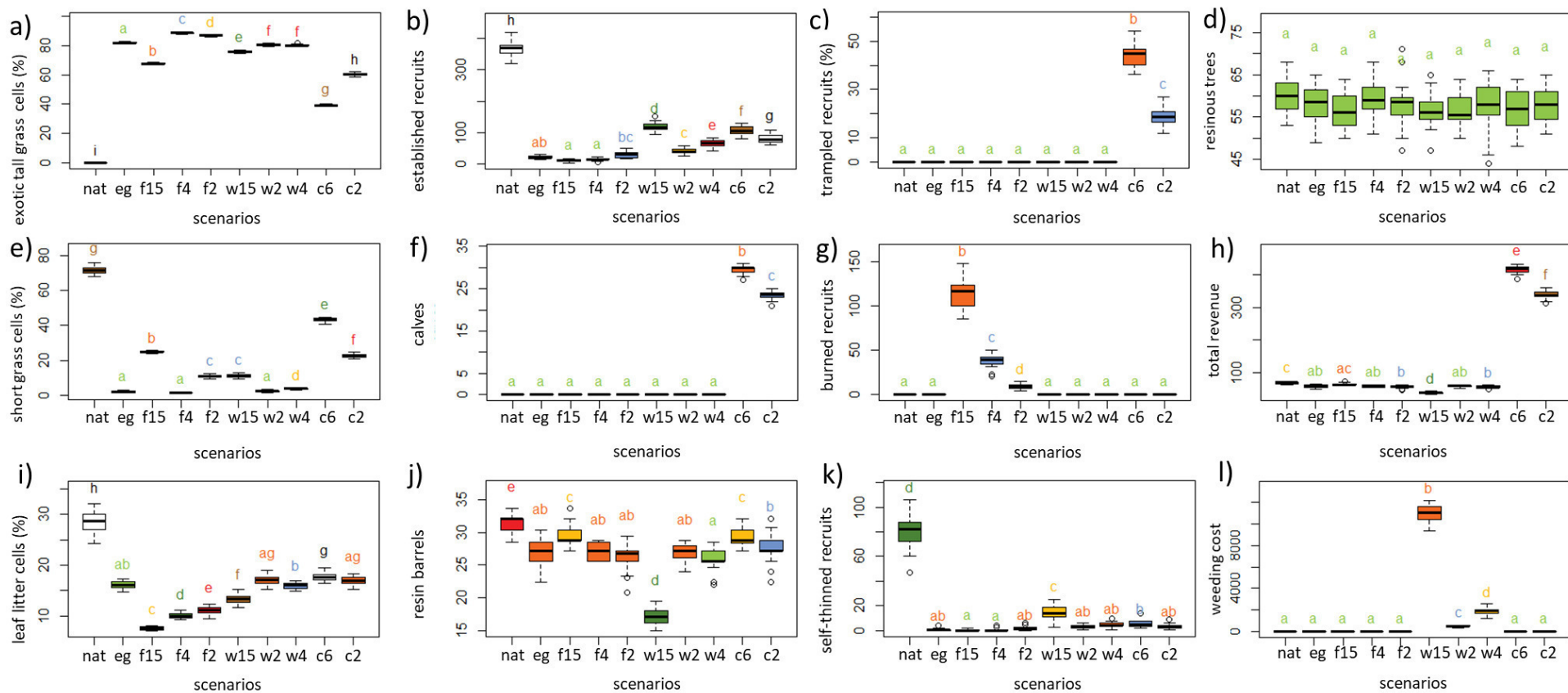
### 4 ha open pasture



### 2 ha open pasture plus 2 ha pine savanna

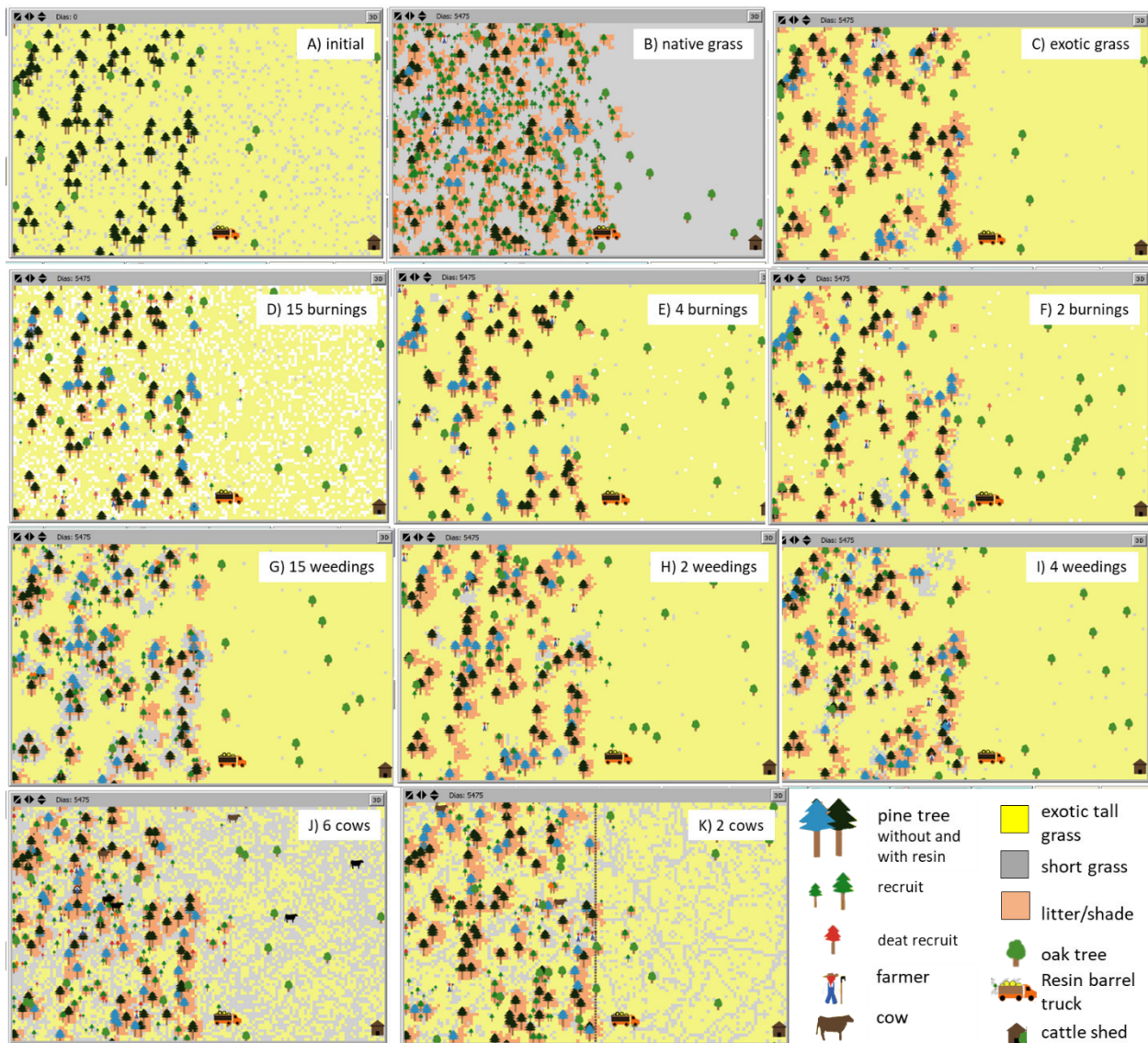


**Fig. 2.** 15-year time series with cattle loads from 0 to 8 (colored lines). Each data point represents the average of 10 repetitions. As described in the main text, in the ABM, we selected and coupled parameters for cow reproduction and exotic grass recovery rate (i.e. transition from short grass to exotic tall grass cell) so that 2 cows would produce (i) 1.0 calves per cow per year in 4 has of open pasture and 0.8 calves in the combination of savanna and open pasture, and (ii) no less than 20% of short grass cells for potential pine recruitment. Under such optimal conditions, in 15 years two cows produced 30 calves, see green line (c). When pine trees were included in the virtual world (2 ha savanna plus 2 ha open pasture), calf production was reduced to 24 calves (d). Figure e) number of short grass cells for 4-hectare open pasture and f) for the mixed range land. Pine needle litter and shade accumulation in 4 ha open pasture land g) and h) for the mixed rangeland 2 ha savanna and 2 ha open pasture.

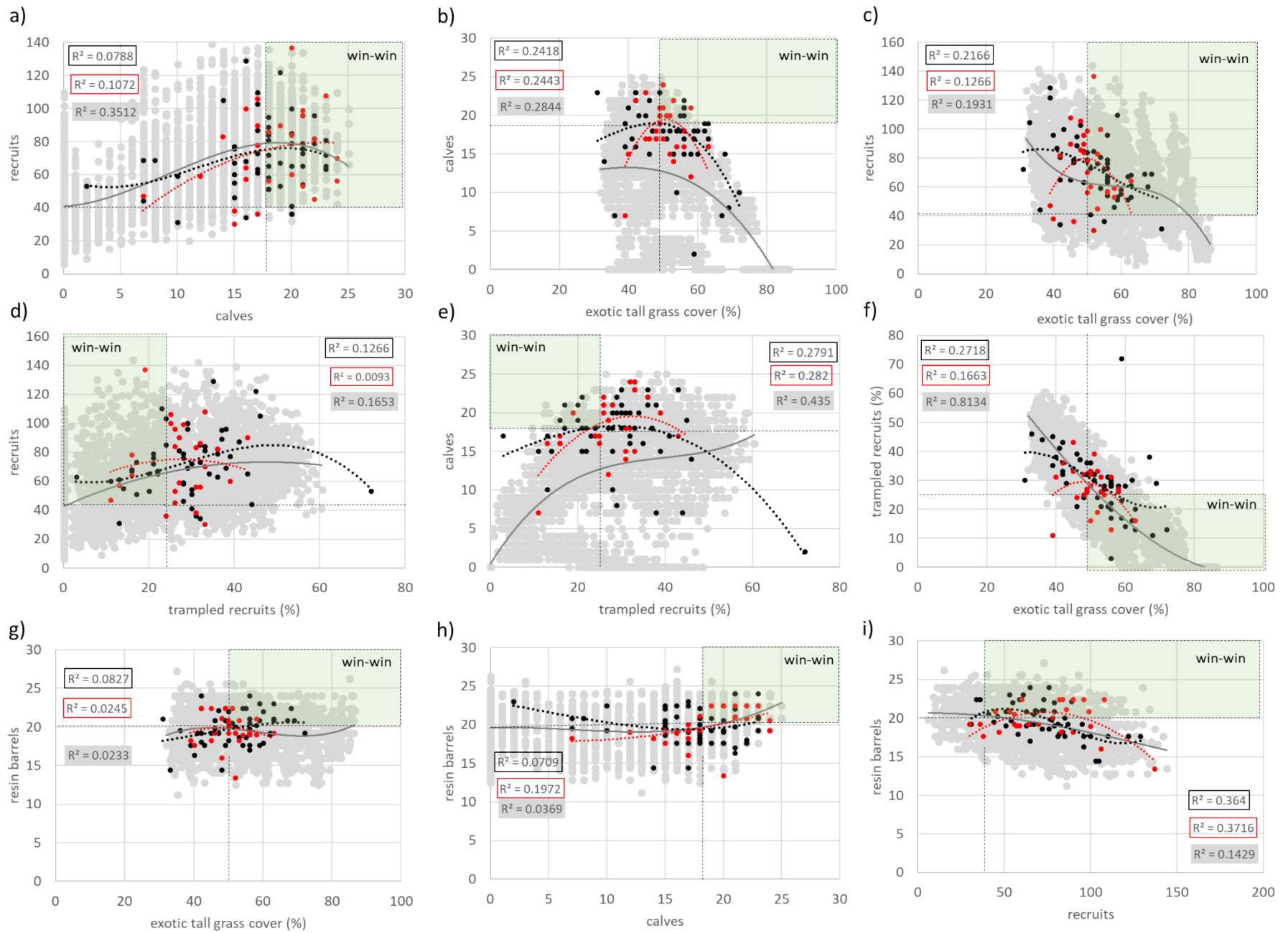


**Fig. 3** The above data displays a broad spectrum of output data for the prediction exercise described in the results section 3.3.2. of the main text: a) percentage of exotic tall grass cells, b) number of established recruits, c) percentage of trampled recruits, d) number of resinous trees, e) percentage of short grass (burnt or browsed) cells, f) calf production, g) number of burned recruits, h) total monetary revenue, i) percentage of leaf litter cells, j) number of resin barrels, k) number of recruits that died due to self-thinning, and l) labor cost of weeding. This sensitivity analysis was run 15 years for 10 scenarios: nat = natural grass cover without management, eg = exotic tall grass cover without management, f + # = number of burnings used to control exotic grass during the 15-year simulation, w + # = number of weeding events used to control exotic grass during the 15-year simulation, and c + # = cattle load with six and two cows, respectively. Each scenario was run 20 times. Scenarios w4 (4 weeding events to control exotic grass cover) and c2 (grazing with 2 cows) were not run in the workshop and therefore are not mentioned in the main text, but are included here to more precisely compare high and low weeding frequency and high and moderate cattle loads. Letters over Box-Whisker plots that share one or more letter label do not differ significantly according to the Tukey HSD multiple mean comparisons test ( $\alpha = 0.05$ ).



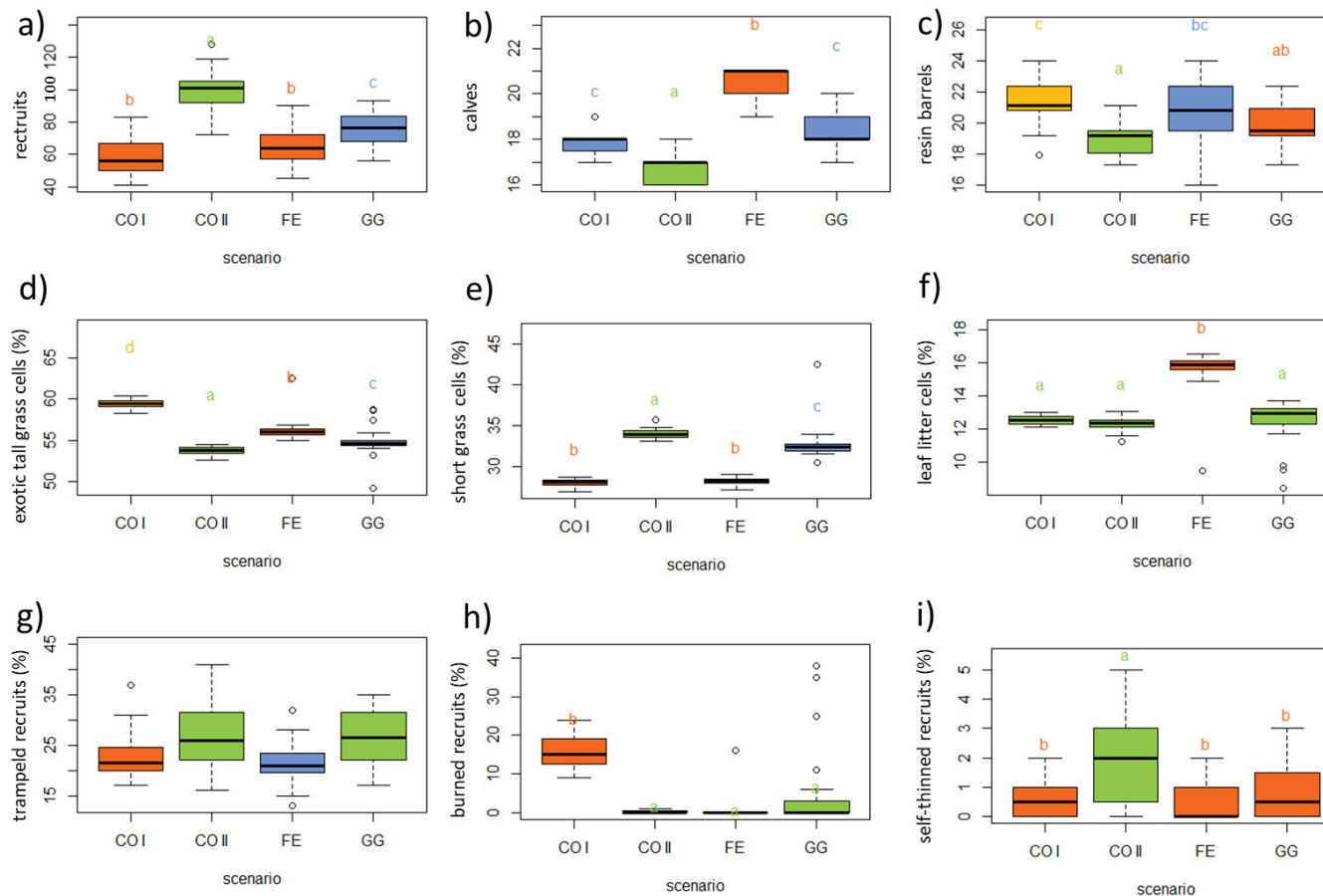


**Fig. 4** Screen shots of 10 scenarios after a 15-year simulation described in figure 3 of this document and in section 3.3.3 of the main text. A = initial condition for all further scenarios: B = native grass cover without management, C = exotic grass cover without management, D = 15 burnings to control exotic grass cover during the 15-year simulation, E = 4 burnings to control exotic grass, F = 2 burnings to control exotic grass, G = annual weeding, H = 2 weeding events over 15 years, I = 4 weeding events over 15 years, J = 6 cows, and K = 2 cows to control exotic grass. Land cover change is not yet clearly visible in these 15-year simulations. These screen shots show similar results as those obtained by workshop participants after a 15-year simulation. During the workshop, screen shots of 30, 50 and 100-year simulations were also displayed to demonstrate possible regime shifts.

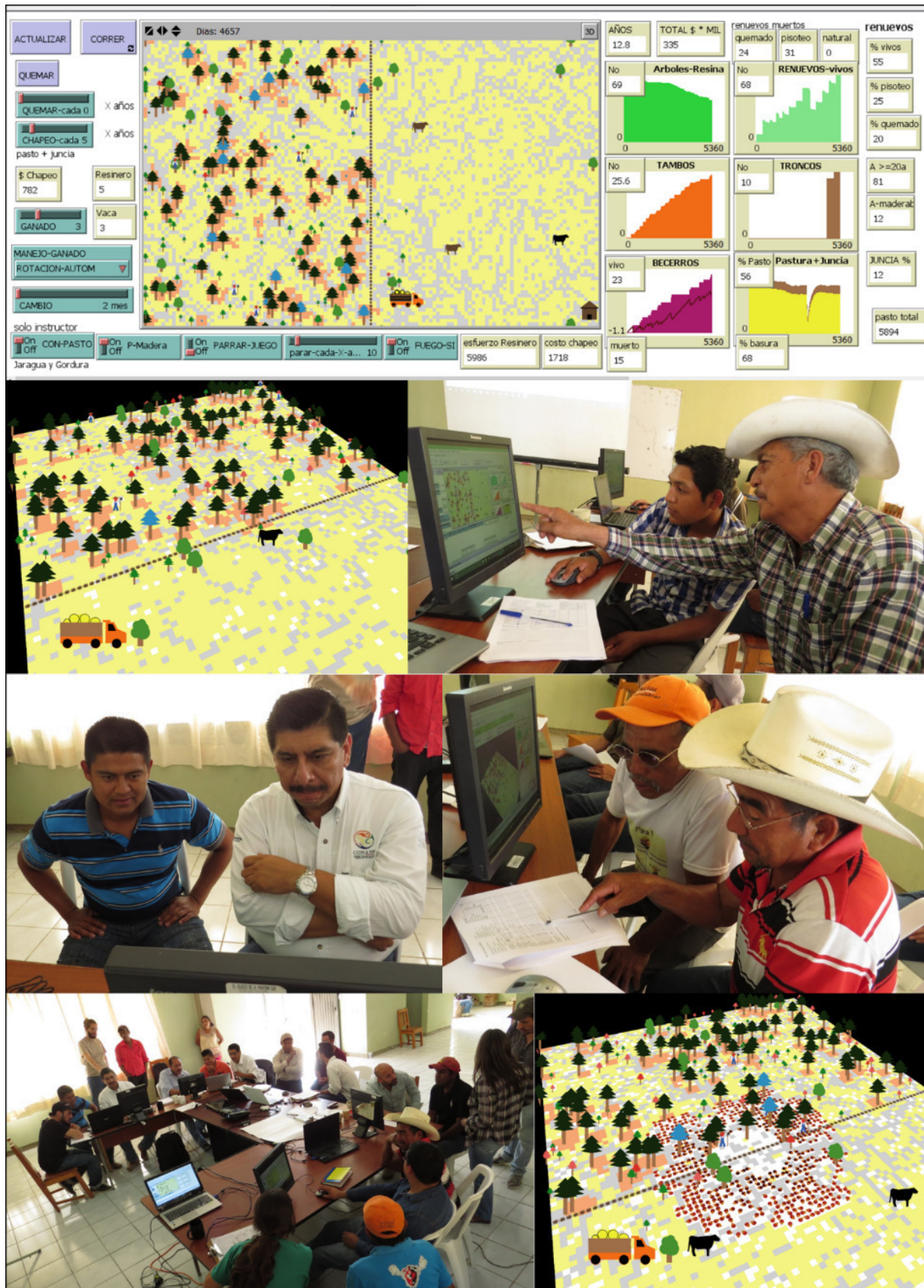


**Fig. 5** Regressions of some ecological and economic outputs for 10-year simulations using different combinations of management strategies. Grey dots and lines, and grey boxes with regression coefficients ( $R^2$ ; polynomial regression), are the result of 3240 possible combinations (runs) for frequency of fire (0, 1, 2, 3, 5, or 10 burnings), weeding frequency (0, 2, 3, 5, or 10 weeding events), cattle load (0 to 8 cows), and frequency of rotation (0, 1, 2, 3, 4, 6, or 12 per year). Black dots and dotted lines, and regression coefficients in boxes with black borders, are the result of the output variables from simulation by workshop participants, as described in section 3.3.3 of the main text. Red dots and lines, and the regression coefficients in boxes with red borders, are the result of the “brother exercise” described in section 3.3.4 of the main text. Quadrants with grey backgrounds represent the win-win area for each possible combination of two variables in the exercise described in section 3.3.3 of the main text: a) established recruits and calf production, b) calf production and exotic tall grass cover, c) recruits and exotic tall grass cover, d) established recruits and percentage of trampled recruits, e) calf production and percentage of trampled recruits, f) percentage of trampled recruits and exotic tall grass cover, g) resin barrels and exotic tall grass cover, h) resin barrels and calf production, and i) resin barrels and established recruits. For the “two brother” exercise, in section 3.3.4 in the main text, goals were slightly different than for the exercise in section 3.3.3 in the main text. For the regression between resin barrels and exotic grass cover, and for that between recruits and calf production, the  $R^2$  value is low because after ten years no correlation exists given that recruitment has not yet had an effect on barrels.





**Fig. 6** Results of a sensitivity analysis for different combinations of management strategies to control exotic grass cover in a pine savanna. In this analysis, cattle load was constant (3 cows) for all four scenarios. Resulting variations are the effect of possible combinations for rotation, weeding, and frequency of fire. Scenario COI consists of 3 cows, no rotation (cattle use both sites), and no weeding or fire. Scenario COII consists of 3 cows, rotation every 4 months, one burning, and 5 weeding events. Scenario FE consists of 3 cows, rotation every 3 months, and no burning or weeding. Scenario GG consists of 3 cows, rotation every 2 months, 4 weeding events, and no burning. These management strategies are examples chosen by workshop participants, as described in section 3.3.3 and Fig. 11 in the main text. Each scenario was run 20 times. While cattle greatly controlled exotic grass cover, the other management strategies – alone or combined - also influenced output data. Letters over Box-Whisker plots that share one or more letter label do not differ significantly according to the Tukey HSD multiple mean comparisons test ( $\alpha = 0.05$ ).



**Fig. 7.** Smallholder farmers and external actors playing TRUE GRASP during a workshop held March 27-29, 2017 in La Sepultura Biosphere Reserve, in Chiapas, Mexico